

Modelling of failures: From chains to coincidences

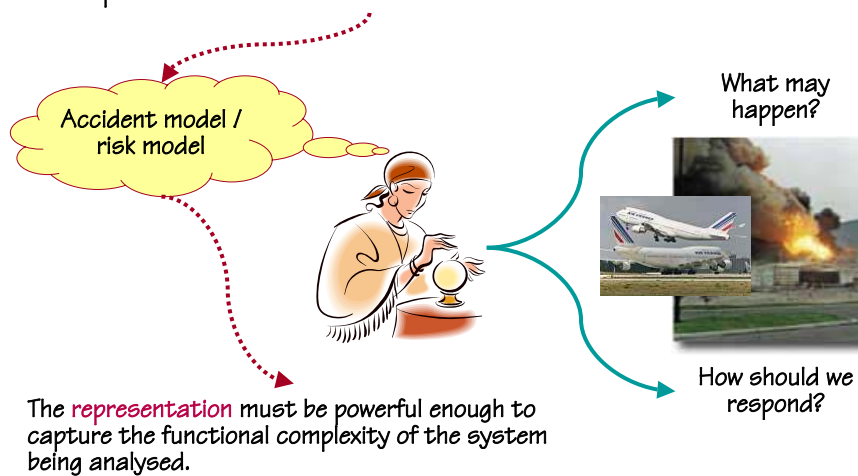
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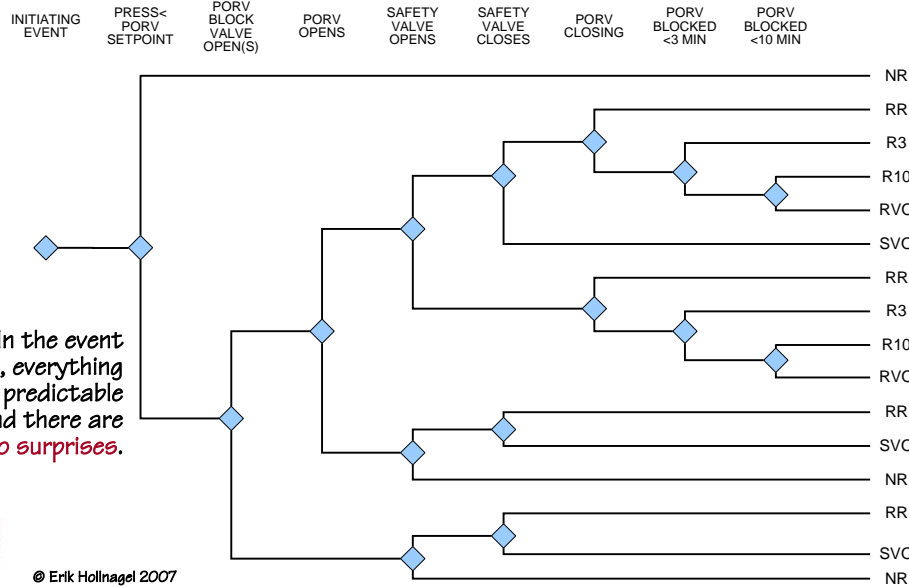
The future is uncertain

Risk assessment requires an adequate **representation** – or model
– of the possible future events.

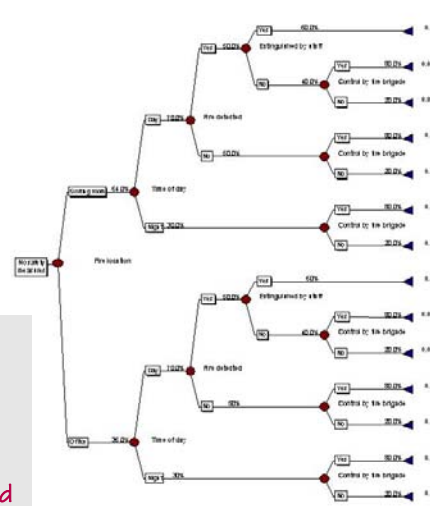
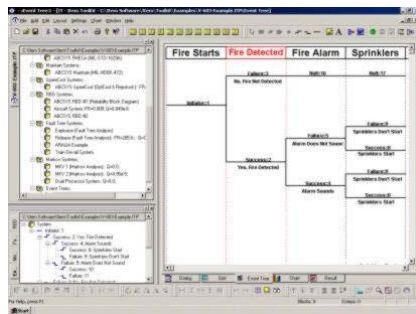


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Typical representation: Event tree

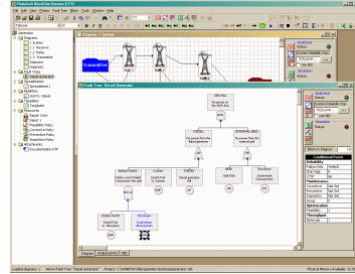
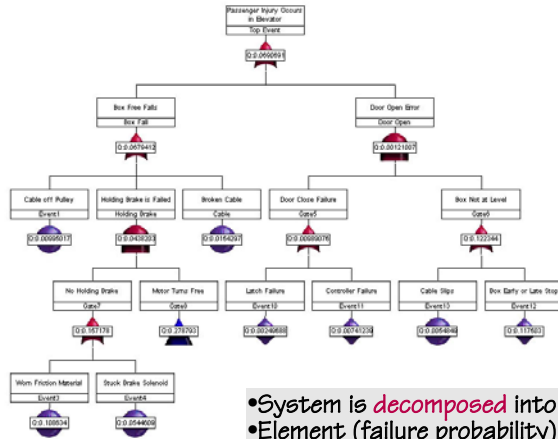


The event tree



- System is **decomposed** into elements (components, events)
 - Element (failure probability) are described **individually**
 - Element functions are **bimodal** (true/false, work/fail)
 - Order (sequence) is **predetermined and fixed**
 - **Linear** (non-interacting) combinations
 - Limited influence from **context/conditions**
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The fault tree



- System is **decomposed** into elements (components, events)
- Element (failure probability) are described **individually**
- Element functions are **bimodal** (true/false, work/fail)
- Order (sequence) is **predetermined** and **fixed**
- **Linear** (non-interacting) combinations
- Limited influence from **context/conditions**



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Nature of technical (formal) systems

Many identical systems



They can be described **bottom-up** in terms of components and subsystems.

Decomposition works for technical systems, because they have been **designed**.

Risks and failures can therefore be analysed relative to **individual components** and **events**.

Output (effects) are proportional to input (causes) and predictable from knowledge of the components. Technical systems are **linear**.



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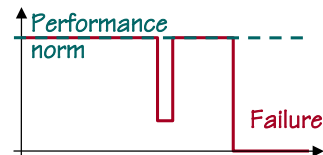
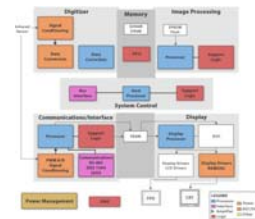
Principle of bimodal functioning

In the technological world, things usually function until they fail. When simple systems, such as a light bulb, fail, they are discarded and replaced by a new (and identical) one.



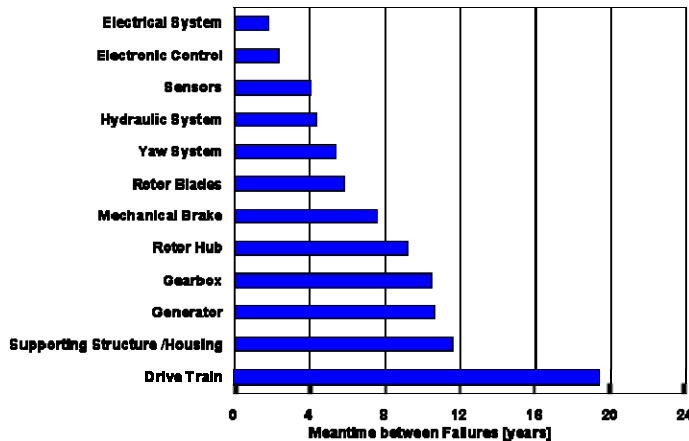
More intricate systems, such as engines, can be maintained and repaired, as long as it is considered worthwhile.

Complex, technological systems work according to the same principle. Failures may, however, be intermittent – especially if complex logic (software) plays a part. Performance is basically **bimodal**: either the system works correctly (as designed) or it has failed.

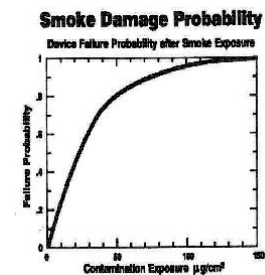


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Technological malfunctions

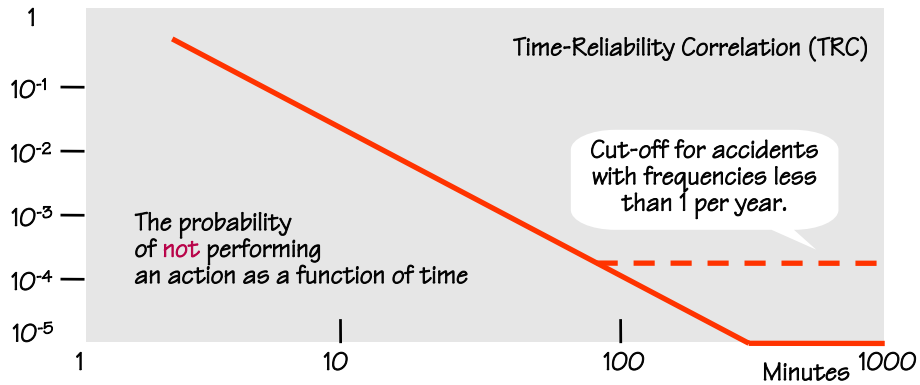


Failure mode
Failure probability
MTBF



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Human malfunctions

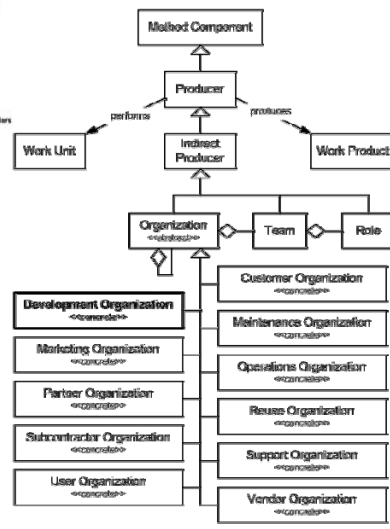
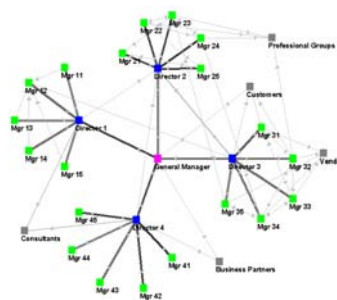


Error of omission (EOO)
Error of commission (EOC)

Failure mode?
Failure probability?
MTBF?



Organizational malfunctions



Failure mode?
Failure probability?
MTBF?



Nature of socio-technical systems

All systems
unique



Must be described **top-down** in terms of functions and objectives.

Decomposition **does not** work for socio-technical systems, because they are emergent.

Risks and failures must therefore be described relative to functional wholes.

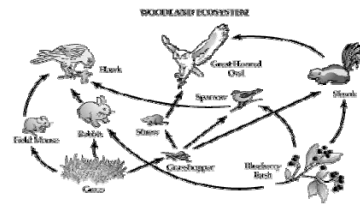
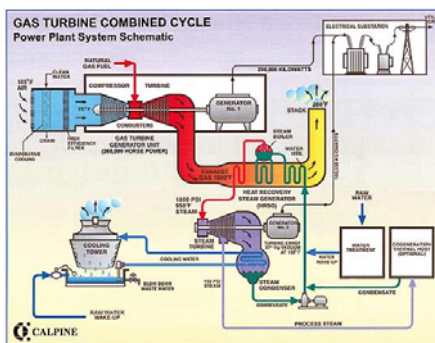
Complex relations between input (causes) and output (effects) give rise to unexpected and disproportionate consequences. Socio-technical systems are **non-linear**.



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What is a system?

A system can be defined as “a set of objects together with relationships between the objects and between their attributes” (Hall & Fagen, 1969, p. 81)



Beer (1964): a manufacturing cell in a garment factory may be considered as a system, as a component of a larger system for garment production, and as containing components, for instance a number of person-cum-scissor units.

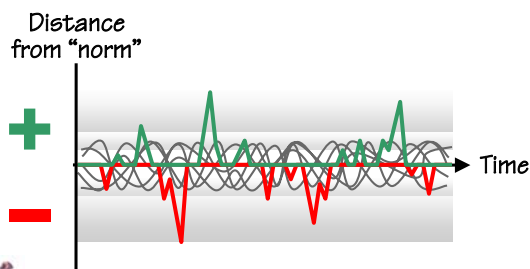
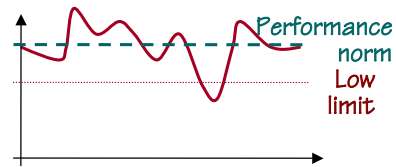
There is no ‘natural’ way of setting the boundary between a system and its environment: it depends on the purpose of the analysis.



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Socio-technical systems are not bimodal

Humans and social systems are not bimodal. Normal performance is variable and this – rather than failures and ‘errors’ – is why accidents happen. Since performance shortfalls are not a simple (additive or proportional) result of the variability, more powerful, non-linear models are needed.



Performance variations can have positive as well as negative outcomes!

Human factors has tended to look for negative aspects of performance - deviations or “errors”



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Traditional view of accidents

The purpose of risk assessment is to identify in a systematic manner how unwanted outcomes can obtain (= severe accidents).

Traditional view:

→ Accidents are due to failures or malfunctions of humans or machines. Example: Event Tree

→ Risks can be represented by linear combinations of failures or malfunctions. Example: Fault Tree



The chain analogy requires that failures are thought of in a bimodal manner, i.e., something breaks the chain or there is an initial initiating event

Traditional risk assessment is constrained by two assumptions.

Events develop in a pre-defined sequence.

The major source of risk is component malfunctions.



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Risk assessment: linear models

Decomposable,
simple linear



Sequential accident model → Probability of component failures

Purpose: find the probability that something “breaks”, either at the component level or in simple, logical and fixed combinations.
Human failure is treated at the “component” level.

Decomposable,
complex linear



Epidemiological accident model → Likelihood of weakened defenses, combinations

Single failures combined with latent conditions, leading to degradation of barriers and defences.

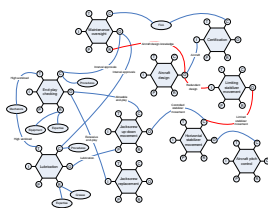
Systemic view of accidents

The purpose of risk assessment is to identify **in a systematic manner** how unwanted outcomes can obtain (= severe accidents).

Systemic view:

Accidents are due to **unexpected combinations** of actions rather than action failures. Example: **ETTO**.

Risks can be represented by **non-linear combinations** of performance variability. Example: **FRAM**.



If failures are seen as a result of combinations of normal performance variability rather than of malfunctions, then the chain analogy is no longer adequate.
An alternative approach must be found that emphasises the dynamic nature of how events develop, i.e., **coincidences** rather than chains.
One possibility is to use **resonance** rather than failure.

Normal behaviour is variable

Social-technical system failures cannot be modelled as **deviations** from required or normal performance:

- humans are **not** designed.
- conditions of work are usually **underspecified**
- humans are multifunctional, and can do many different things

Accounting for the sources and range of **normal performance variability**:



Inherent variability (psychological / physiological phenomena).
 Ingenuity and creativity – adaptability (overcoming constraints and underspecification).
 Organizationally induced performance variability (meeting demands, stretching resources).
 Socially induced variability (meeting expectations, informal work standards).
 Contextually induced performance variability (performance conditions).



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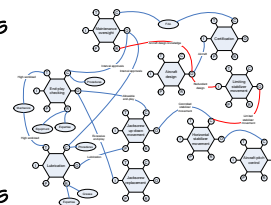
Risk assessment: non-linear models

Performance variability is **natural** in socio-technical systems, and a valuable part of normal performance. The many small adjustments enable humans to **cope** with the complexity and uncertainty of work.

The adjustments allow the system to achieve its functional goals more efficiently by **sacrificing** details that under normal conditions are unnecessary. Humans are adept at developing working methods that allow them to take shortcuts, thereby often **saving** valuable time.

Accounting for how performance variability may combine:

- Functional resonance** (unintended, non-linear outcomes of normal performance adjustments).
- Actions based on expectations (of what others **have done** or **will do**)
- Unanticipated consequences** (exact predictions impossible)
- Combinations** of “unsafe” actions and latent conditions



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Traffic and randomness

Traffic is a system in which millions of cars every day move so that their driving paths cross each other and critical situations arise due to pure random processes: cars meet with a speed difference of 100 to more than 200 km/h, separated only by a few meters, with variability of the drivers' attentiveness, the steering, the lateral slope of the road, wind and other factors.



Drivers learn by experience the dimensions of the own car and of other cars, how much space is needed and how much should be allocated to other road users, the maximum speed to approach a curve ahead, etc. If drivers anticipate that these minimum safety margins will be violated, they will shift behavior.

The very basis of traffic accidents consists of random processes, of the fact that we have complicated traffic system with many participants and much kinetic energy involved.

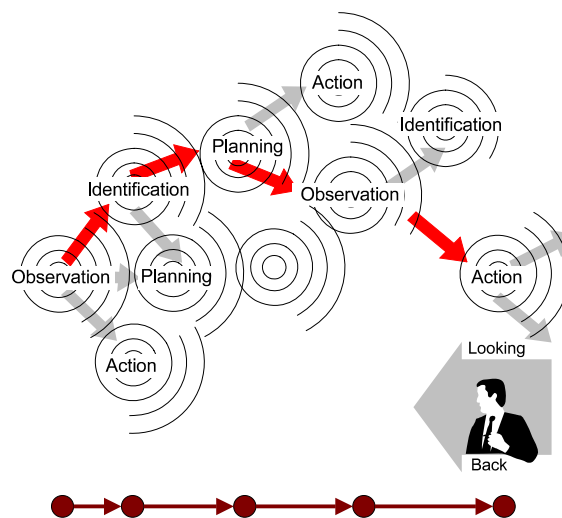
When millions of drivers habitually drive at too small safety margins and make insufficient allowance for (infrequent) deviant behavior or for (infrequent) coincidences, this very normal behavior results in accidents.



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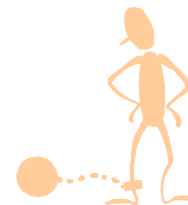
Summala (1985)

Looking back only ONE thing happened



Given the actual context, the events seem to describe an orderly sequence.

The order (chain of events) is, however, an *artefact* due to the asymmetry of time

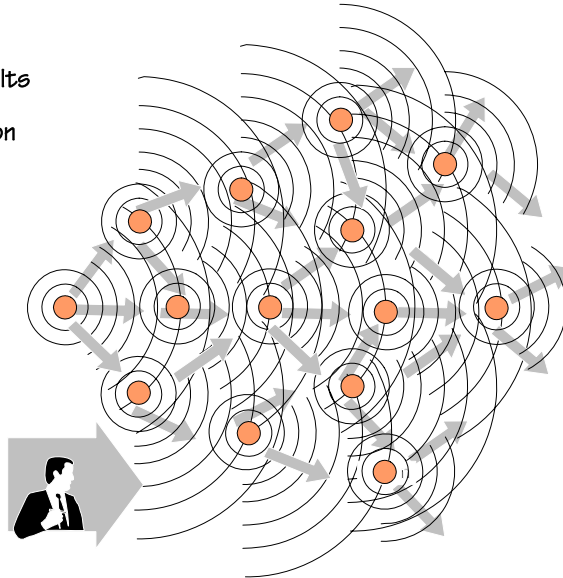


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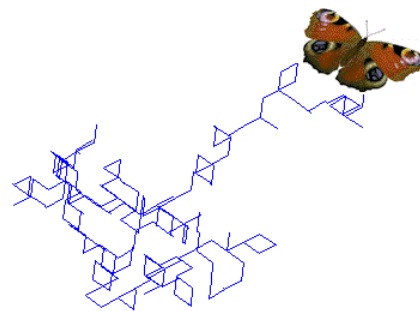
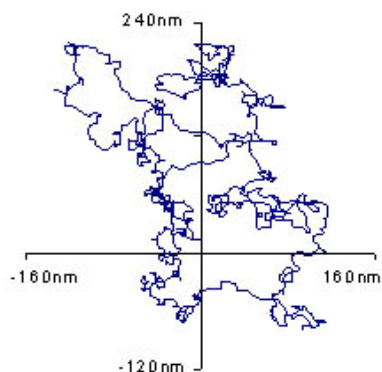
Looking ahead ANYTHING can happen

Prediction that is not constrained, is basically a **combinatorial** effort. The results therefore represent the complexity of the classification system, rather than real performance.

Actions are more often determined by the **final** cause (telos) than by the **efficient** cause. Causal chains are thus of an **a posteriori** rather than an **a priori** nature.

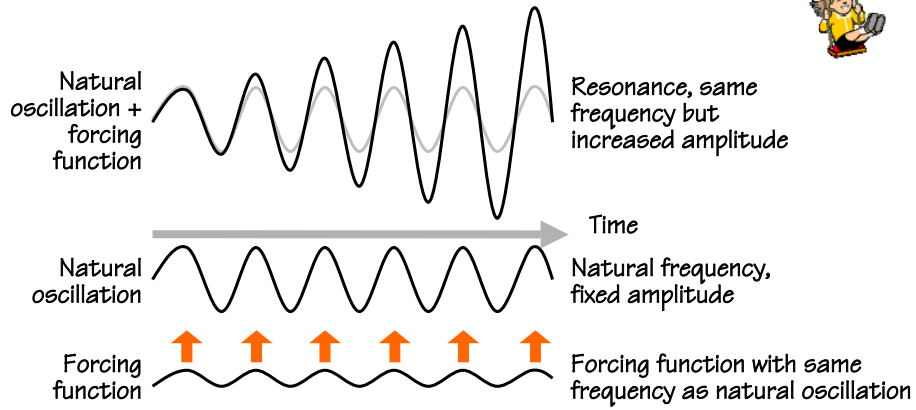


The future as non-linear events



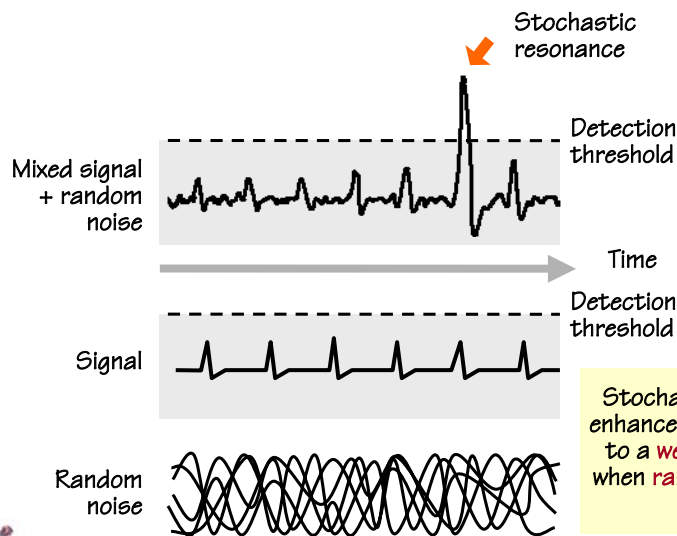
Non-linear events have been likened to Brownian movements or random walks. Risk assessment requires something that is non-linear (non-trivial) at the same time as it is systematic (predictable)

Resonance



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Stochastic resonance



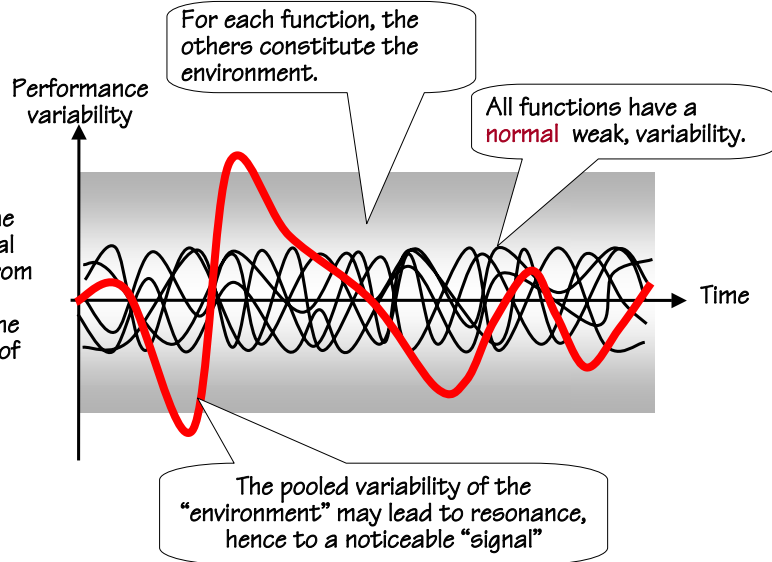
Stochastic resonance is the enhanced sensitivity of a device to a **weak signal** that occurs when **random noise** is added to the mix.



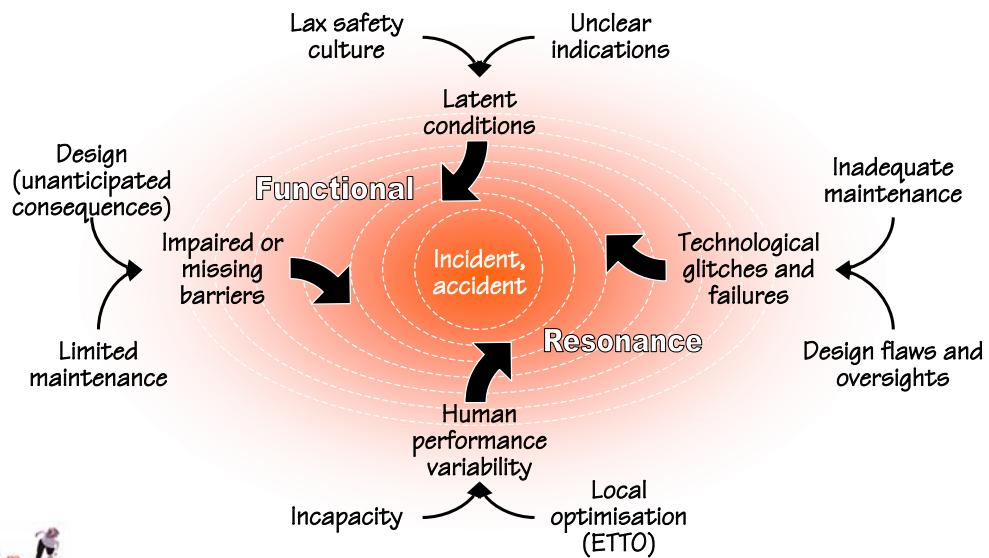
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Functional resonance

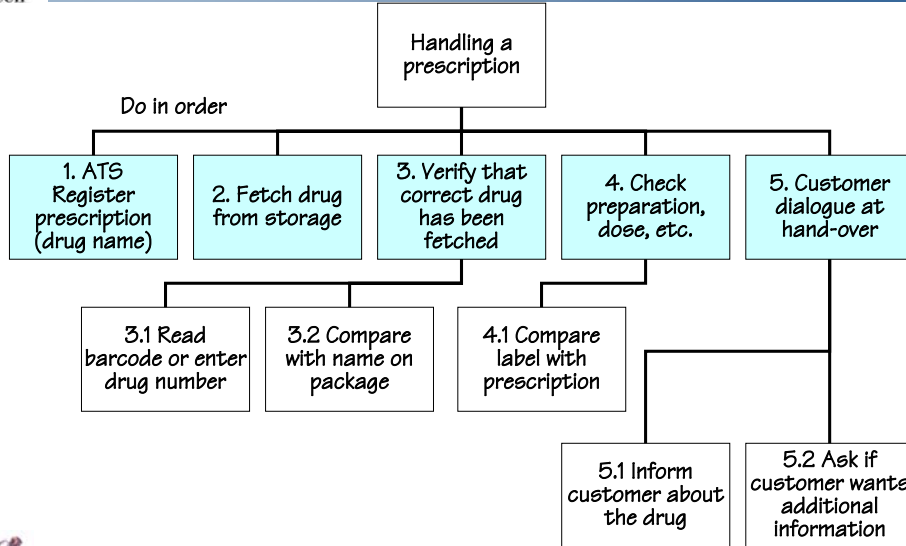
Functional resonance is the **detectable** signal that **emerges** from the **unintended** interaction of the **weak variability** of many signals.



Functional Resonance Accident Model

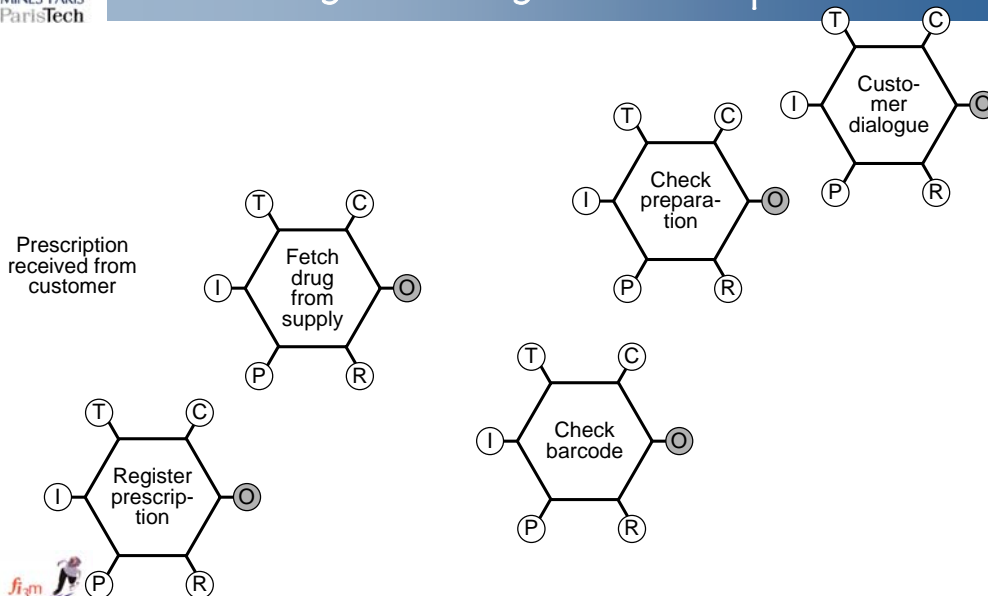


Handling drug prescriptions (HTA)



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Drug handling – normal procedure



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Conclusions

Risk assessment must comprise a model of the system and its behaviour, which is as complex as the system itself.

- Conventional risk assessment is based on linear models (e.g., event tree) and on calculating failure probabilities.
- Socio-technical systems are non-linear. Risk is an emergent rather than a resultant phenomenon.

Risk assessment should address how irregularities can arise from normal performance variability, rather than on how individual functions fail.

- Performance variability reflects the nature of the work environment, including social and organisational factors.
- Performance variability is predictable for identified conditions.

The principle of **functional resonance** can be used to identify possible combinations of performance variability which may lead to the occurrence of undesirable outcomes.



Three premises of resilience engineering

- ➔ **Performance conditions are always underspecified.**
It is impossible to specify in every detail what should be done and how. Individuals and organisations must therefore always **adjust** their performance to the current conditions; and because resources and time are **finite**, such adjustments will inevitably be **approximate**.
Performance variability is unavoidable, but it is a source of **successes** as well as of failures.
- ➔ **Many adverse events can be attributed to a breakdown or malfunctioning of components and normal system functions, but many cannot.**
These are best understood as the result of unexpected combination of normal performance variability. Adverse events therefore represent the converse of the adaptations necessary to cope with the complexity of the real world.
- ➔ **Effective safety management cannot be based on hindsight, nor rely on error tabulation and the calculation of failure probabilities.**
Safety management must be proactive as well as reactive. Resilience Engineering looks for ways to enhance the ability of organisations to create processes that are robust yet flexible, to monitor and revise risk models, and to use resources proactively in the face of disruptions or ongoing production and economic pressures.



Resilience engineering

➔ Resilience requires an organisation that at all times is:

Responsive - able to respond effectively when something happens

Attentive - knows what to look for and regularly updates its knowledge, competence and resources

Looking ahead - prepared for what might conceivably happen in the future in both the short and the long term.

➔ The development and application of Resilience Engineering requires

The ability to **measure, monitor, and analyse** the resilience of an organisation in its operating environment,

Tools and methods to **improve** an organisation's resilience vis-à-vis the environment, and finally

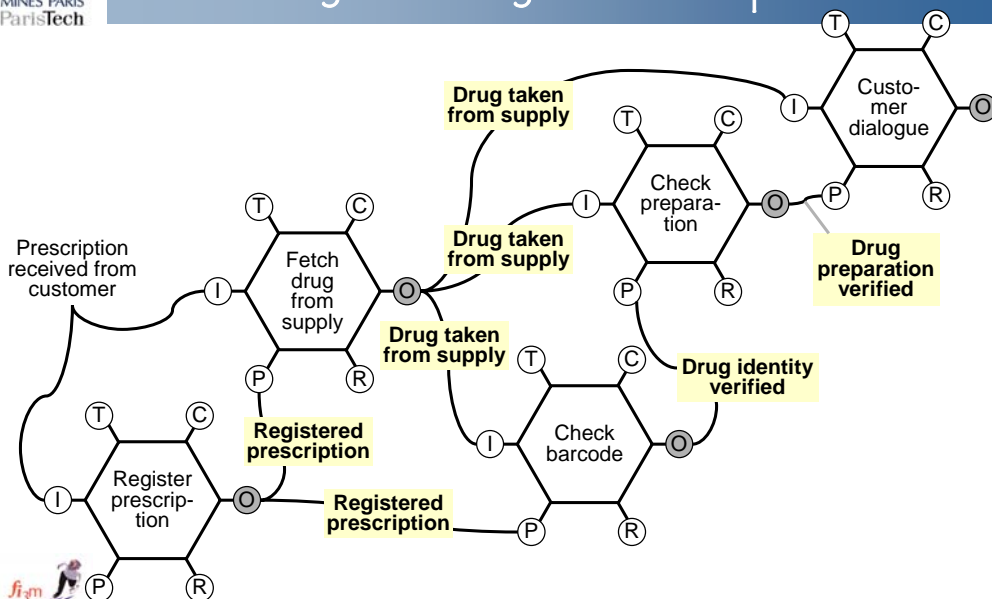
Techniques to **model** and predict the short- and long-term effects of changes to operational, organisations, and targets..

➔ The purpose of safety management is not to **reduce** risks or the number of adverse events, but to **increase** on all levels the ability to adjust performance in the face of changes, disturbances, and uncertainty.

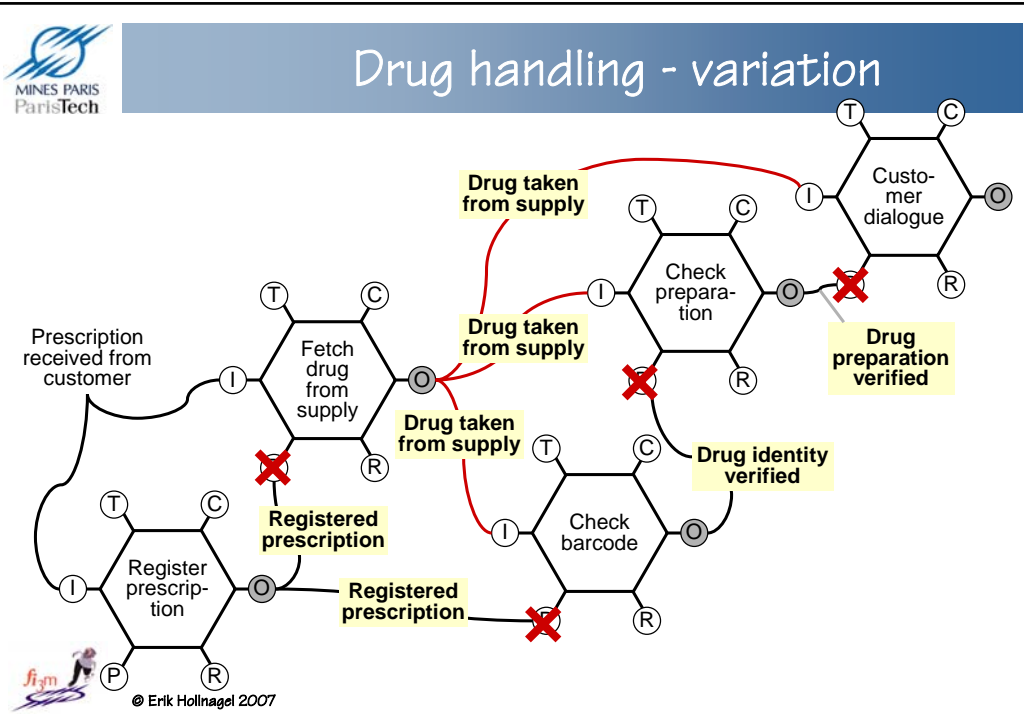


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Drug handling – normal procedure



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Important announcement

MINES PARIS ParisTech

EUROCONTROL
European Organisation for the Safety of Air Navigation

DFS Deutsche Flugsicherung

MINES PARIS ParisTech

Ph.D. Position
 “A resilience based approach to evaluate the human contribution to system safety”

The position is part of a new project in a collaboration between Eurocontrol, Deutsche Flugsicherung (DFS), and École des Mines de Paris, Pôle Cindyniques.
 The main place of work will be Sophia Antipolis, France

For further information please contact either:
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Thank you for your attention

