

On a framework for modeling and analyzing interdependencies in Electrical Power Systems

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Outline

- ❖ **Context and objectives**
- ❖ **Description of the Electrical Power System**
 - The electrical infrastructure
 - The Information technology based control system
- ❖ **Failure model of EPS**
- ❖ **State definition for EI and ITCS**
- ❖ **The Interdependencies between EI and ITCS**
- ❖ **Relevant aspects of the EPS modeling framework**
- ❖ **Feasibility study**
- ❖ **Conclusions and next steps**

The context - 1

- Economy, security and quality of life increasingly depend on the resiliency of a number of **critical infrastructures**
- **Critical infrastructures** are complex collections of interacting systems and components, communicating through multiple heterogeneous networks
- **Interdependencies** increase vulnerability, as they give rise to multiple error propagation channels from one infrastructure to another
- Therefore, the **impact of infrastructure components failures** and their **severity** can become much higher and more difficult to foresee compared to failures confined to single infrastructures

→ Analysis of infrastructures components interactions is crucial to understand and characterize interdependencies

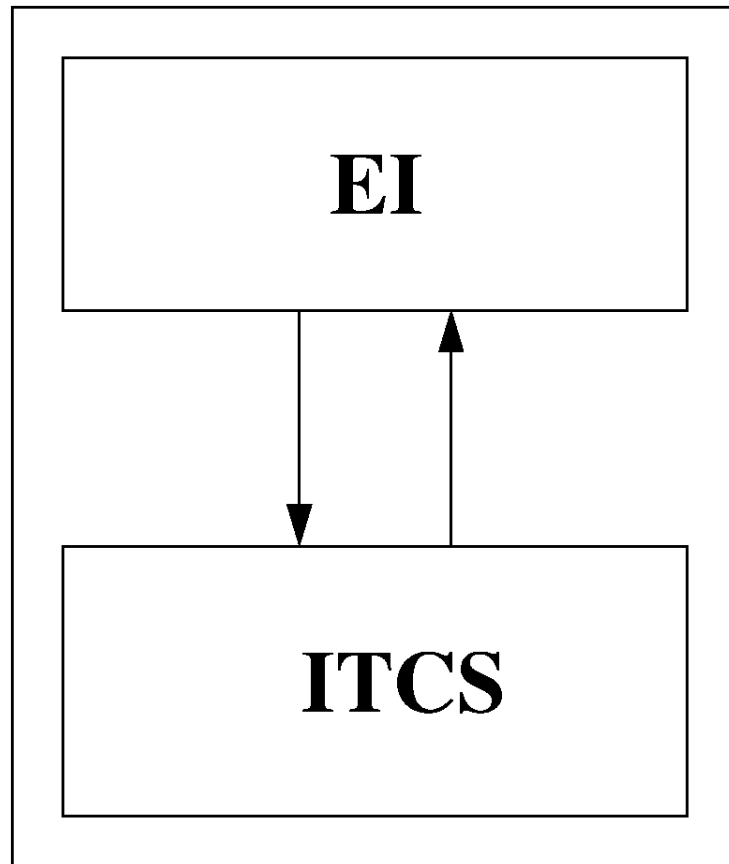
The context - 2

- **Electrical Power Systems** are prominent representatives of CI
- Interdependencies between the electrical power grid (**EI**) and the control system infrastructure (**ITCS**) have been responsible of major power grid blackouts
- The Consortium for Electric Reliability Technology Solutions (**CERTS**) is particularly active in studying cascading failures
- However, existing models **do not explicitly account for** the complex interactions between EI and ITCS
- The EU STREP 027513 **CRUTIAL** project is addressing the analysis and management of interdependencies and of the resulting operational risk

Objective

- Define a conceptual **modeling framework** well suited to characterize and analyze the **interdependencies** between
 - the information infrastructure
 - the controlled power infrastructure
- The focus is on **interdependence-related failure**:
 - Cascading failures
 - Escalating failures
 - Common-cause failures
- The goal is to **quantitatively assess** their impact on the resilience of these infrastructures

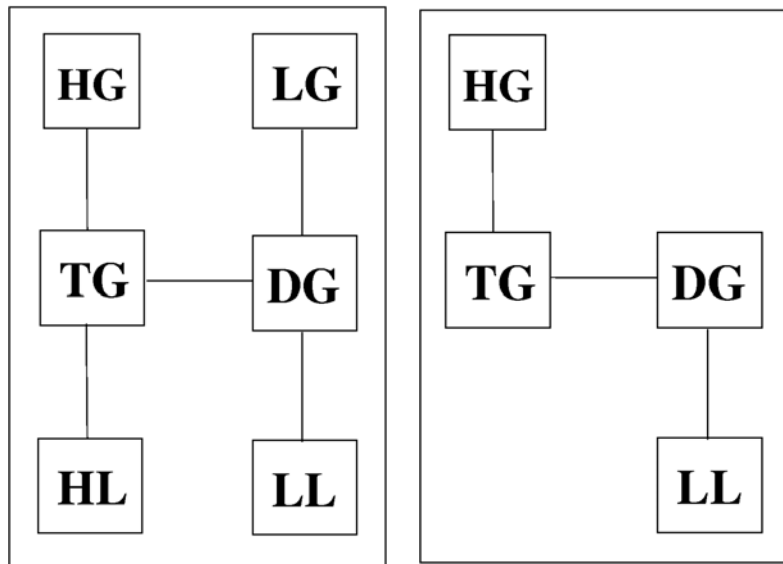
Electrical Power System (EPS) characterization



- The EPS system can be seen as composed of two interacting sub-systems:
 - The **Electric Infrastructure (EI)**;
 - The **Information Technology Based Control System (ITCS)**.
- An event (e.g. failure or recovery) that occurs in one sub-system can “affect” the behavior of the other sub-system (**interdependencies**).

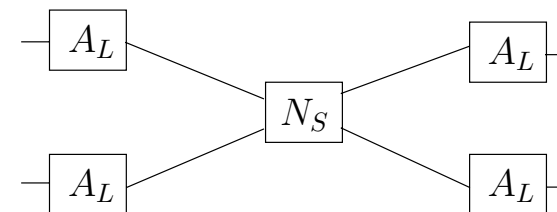
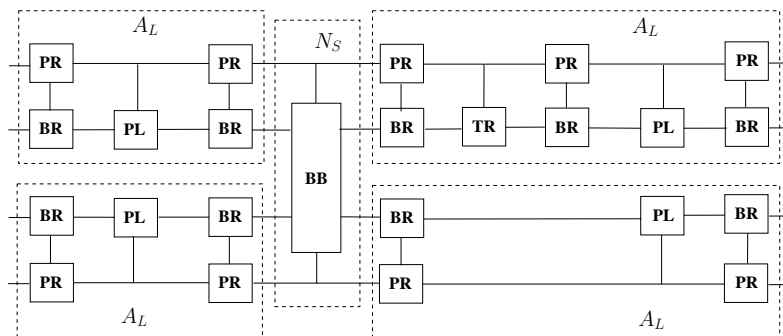
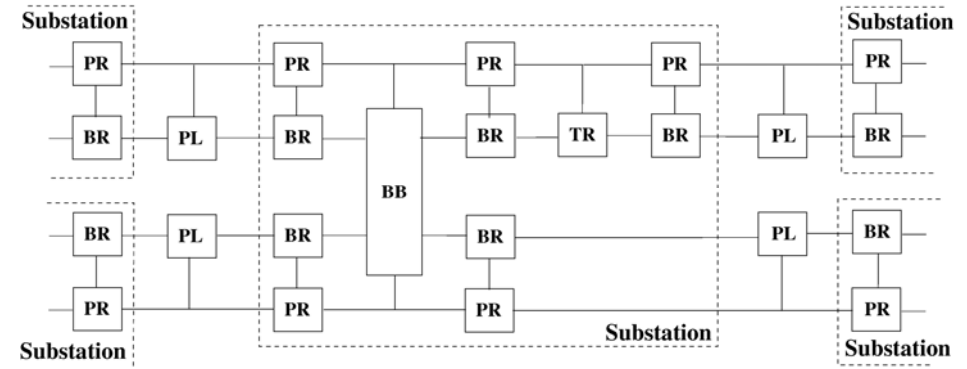
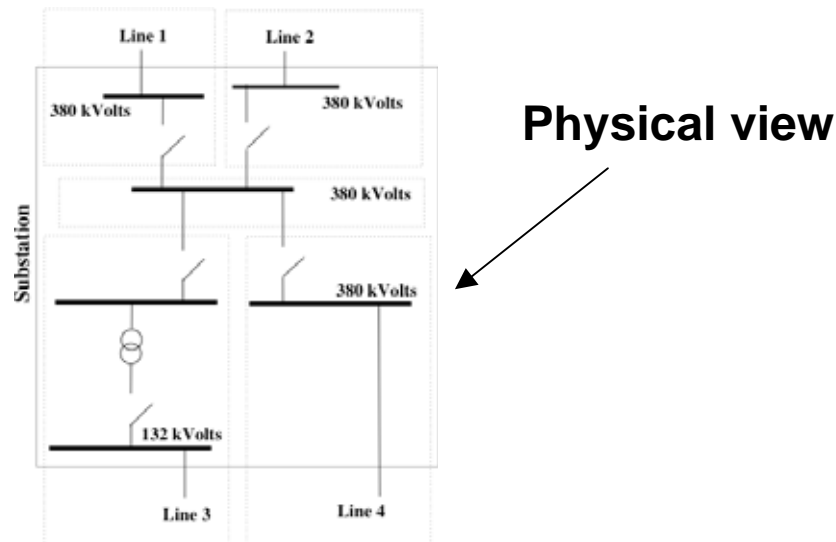
The Electrical Infrastructure

The **EI** produces and transports the electric power to the final users

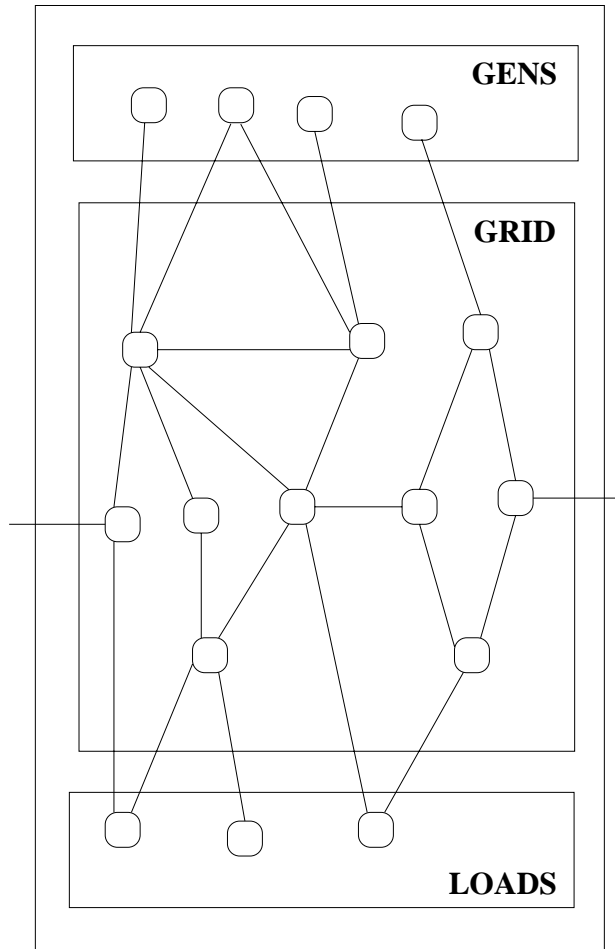


- **HG**: high voltage generation plant
- **LG**: medium/low voltage generation plant
- **TG**: transmission grid
- **DG**: distribution grid
- **HL**: huge voltage load
- **LL**: medium and low voltage load

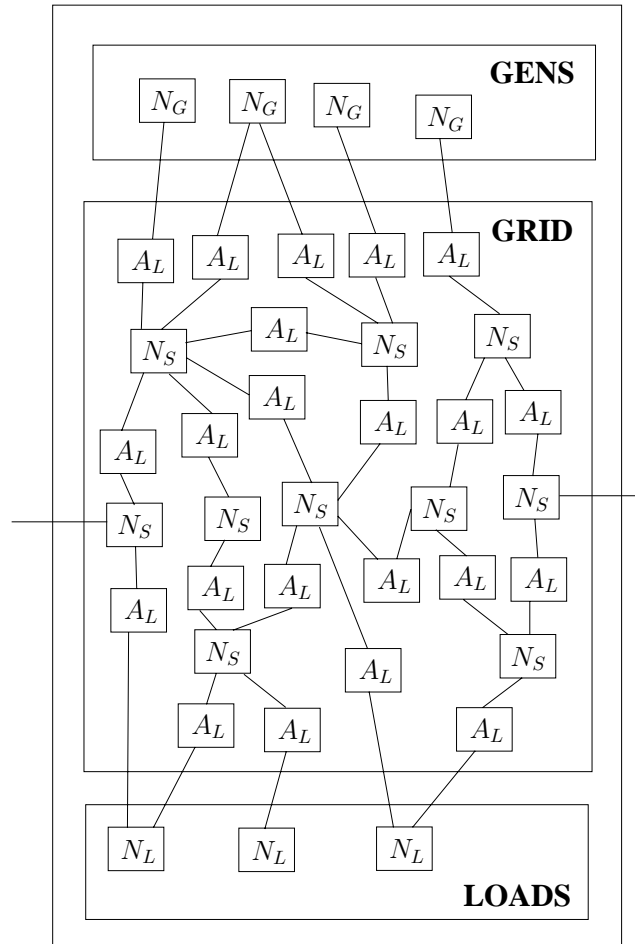
Focusing on substation and power lines



Example of Topology for a TG



meshed graph



Logical scheme

The ITCS system

ITCS is in charge of:

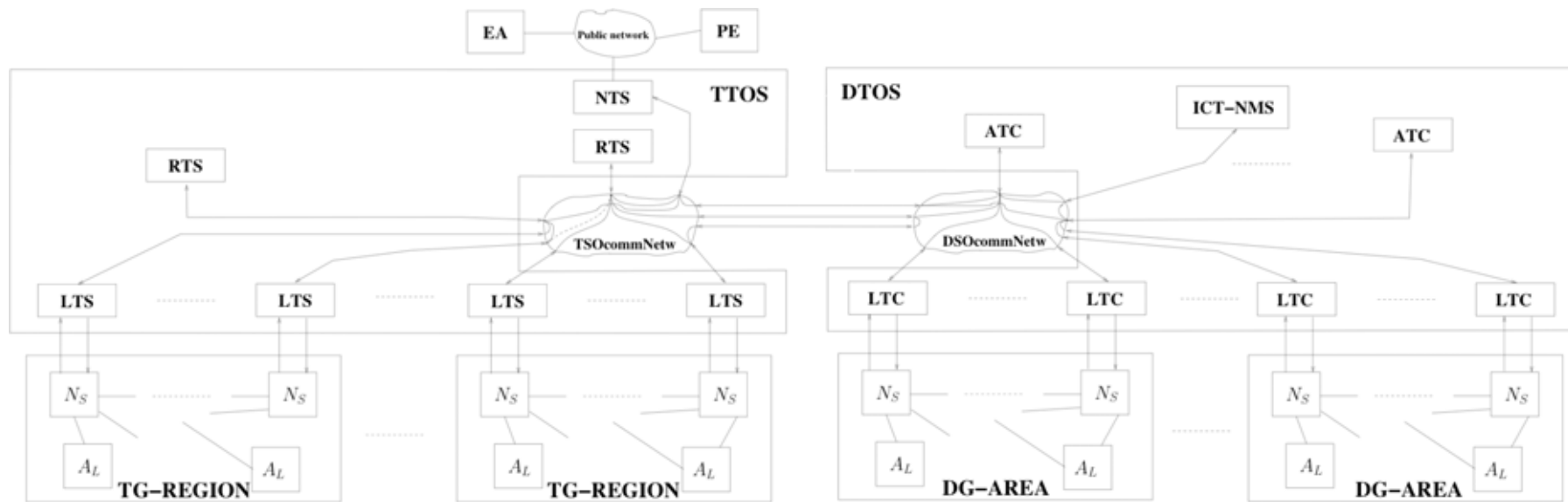
- Assuring availability of EI
- Enhancing QoS (frequency and voltage regulation)
- Optimizing generators and substations management

Logical components of ITCS:

- Protection system;
- Frequency and voltage regulation systems;
- Tele-operation systems (DTOS for the DG and TTOS for the TG)

The logical ITCS components interact through a hierarchical structure, using public and/or private networks to exchange exchange grid status information and control data

Logical structure of TTOS and DTOS



LTS (Local Tele-control System), **RTS** (Regional Tele-control System) and **NTS** (National Telecontrol System) of TTOS,
LTC (Local Tele-control System) and **ATC** (Area Tele-control System) of DTOS

These components differ for their criticality and for the locality of their decisions.

El Failure Model

1. **Transient or permanent disconnection** of a component N_S , N_G , N_L and A_L **with consequent disconnection** of one or more components from the grid. **Transient or permanent failed disconnection** of a component N_S , N_G , N_L and A_L **without isolation** from the grid.
2. **Transient or permanent overloads** of N_S and A_L . **Unexpected reduction of production** of N_G . **Unexpected increase or reduction of demand** of N_L . **Voltage collapse**. **Under-frequency and loss of synchronism**.

Disconnections imply changes in the topology T of the grid and consequent changes of V , F , I , A , P and Q .

The disruptions at point 2 represent changes of the electrical parameters of the components of the grid N_S , N_G , N_L and A_L and do not necessarily imply changes in T .

ITCS Failure Model

- **The failures of the ITCS components can be summarized in:**
 - omission failure,
 - time failure,
 - value failure and
 - byzantine failure.

Here the focus is on the failures and not on their causes (internal HW/SW faults, malicious attacks, etc.).

State definitions

- EI status is defined by an **hybrid state** S_{EI} :

$$S_{EI} = (\textit{discrete part}; \textit{continuous part})$$

In particular: $S_{EI} = (T; V, F, I, A, P, Q)$,

where

T=Topology of the grid

V,F,I,A,P,Q= Voltage, Frequency, Current flow, Angle, Active and Reactive Power

- ITCS status is defined by a **discrete state** S_{ITCS} :

$$S_{ITCS} = (\textit{discrete part})$$

E.g.: $S_{ITCS} = (\text{Working, Partially failed, Lessened, Recovery, ...})$

Why an hybrid state for EI?

- **The electrical values associated to an EI component** (e.g. voltage, current flow, ...) **are important**, since they influence:
 - The time to disruption of the component
 - The correct application of a protection
 - The type of reconfiguration action to be applied (more or less “aggressive”, timed-constrained, ...)
 - ...
- **The topology of the EI is important**, since it influences:
 - The propagation of a disruption from an EI component to its contiguous components
 - The type of reconfiguration action to be applied (local, regional, national, ...)
 - ...

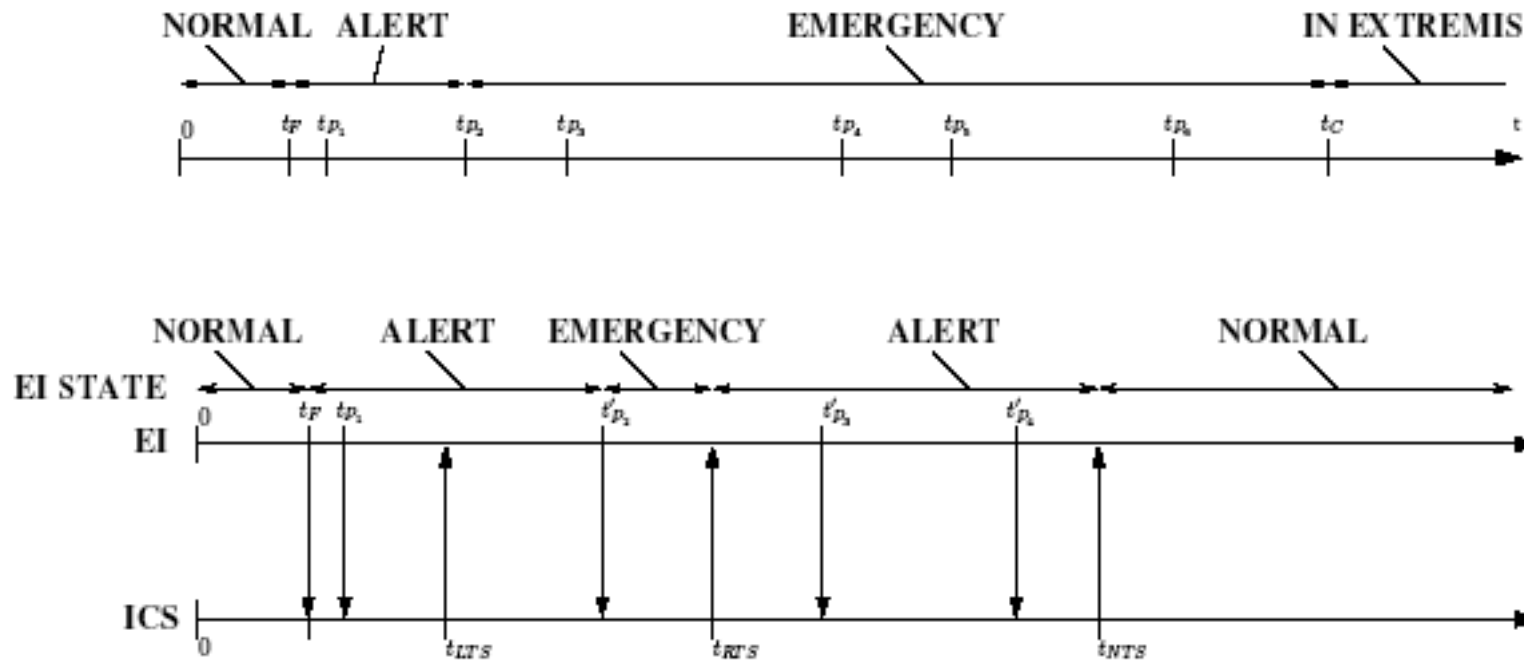
Causes of state changes

- **The state of EI changes in case of:**
 - Disruption of an EI component
 - Activation of a local protection
 - Reconfiguration action by ITCS (including erroneous, delayed or not required reconfiguration)
- **The state of ITCS changes in case of:**
 - Failure/recovery of an ITCS component
 - Disruption of the EI

Interdependencies

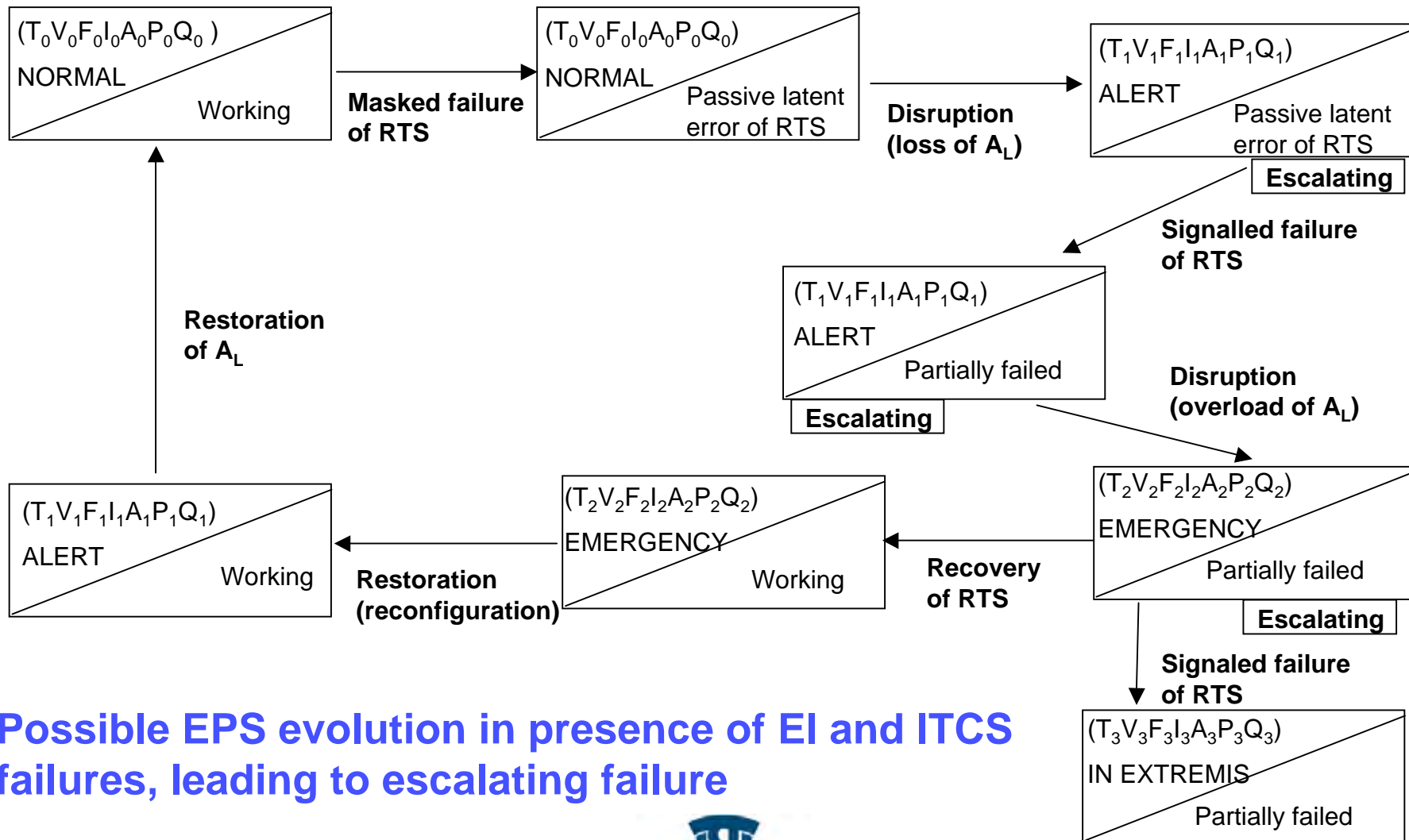
- $S_{ITCS} \rightarrow S_{EI}$
 - Impact on T and/or the values of V, F, I, A, P, Q
 - E.g. a value failure of LTS (incorrect closing or opening of the power line A_L) - such failure can also impact on connected RTS components
- $S_{EI} \rightarrow S_{ITCS}$
 - E.g. a failure in the EI causes a partial black-out that could reduce the performance of the private or public networks used by ITCS, or isolate part of the ITCS.
- $(S_{EI} \text{ and } S_{ITCS}) \rightarrow (S_{EI} \text{ or } S_{ITCS})$
 - E.g. an ITCS component fails (omission failure) and does not isolate an EI component affected by a disruption
 - ➔ the grid topology changes (the disruption propagates and a set of contiguous EI components becomes disrupted)

Dynamic behavior of EPS



Where **NORMAL**, **ALERT**, **EMERGENCY** and **IN EXTREMIS** are EI operative states with increasing criticality from **NORMAL** (all constraints are satisfied) to **IN EXTREMIS** (service partially or totally interrupted)

Dynamic behavior of EPS - 2



Possible EPS evolution in presence of EI and ITCS failures, leading to escalating failure

Focus on the modeling framework - 1

- ❖ It should be able to capture **structural** and **behavioral** aspects of EPS components
- ❖ Major identified characteristics, grouped in:
 - Modeling power aspects
 - Modeling efficiency aspects
 - Solution power aspects

Focus on the modeling framework - 2

Modeling power aspects

❖ The framework should support:

- A1.** Different formalisms for different sub-models
- A2.** Representation of continuous and discrete states
- A3.** Time and probability distributions and enabling conditions can depend on both the continuous and the discrete state
- A4.** Call to functions implementing the reconfiguration, regulation and auto-evolution algorithms
- A5.** Definition of (performability) measures, appropriate for EPS risk analysis

Focus on the modeling framework - 3

Modeling efficiency aspects

❖ The framework should support:

- B1.** Hierarchical composition of different sub-models
- B2.** Replication of (anonymous and non-anonymous) sub-models (sharing a common state)
- B3.** Compact representation of the grid topology (e.g. using incidence matrix [nodes x arcs])
- B4.** Compact representation of the electrical parameters (V,F,I,A,P,Q) (e.g. through arrays of real-values)

Focus on the modeling framework - 4

Solution power aspects

❖ The framework should support:

- Analytical solution of the overall model (if feasible).
Possible problems:
 - State-space explosion
 - Stiffness
 - Unavailable analytical methods for the considered class of models - **more applicable to simpler sub-models**
- Simulation
 - by automatic tools
 - by ad-hoc simulation software
- Separate evaluation of different sub-models and combination of the results

Feasibility study - 1

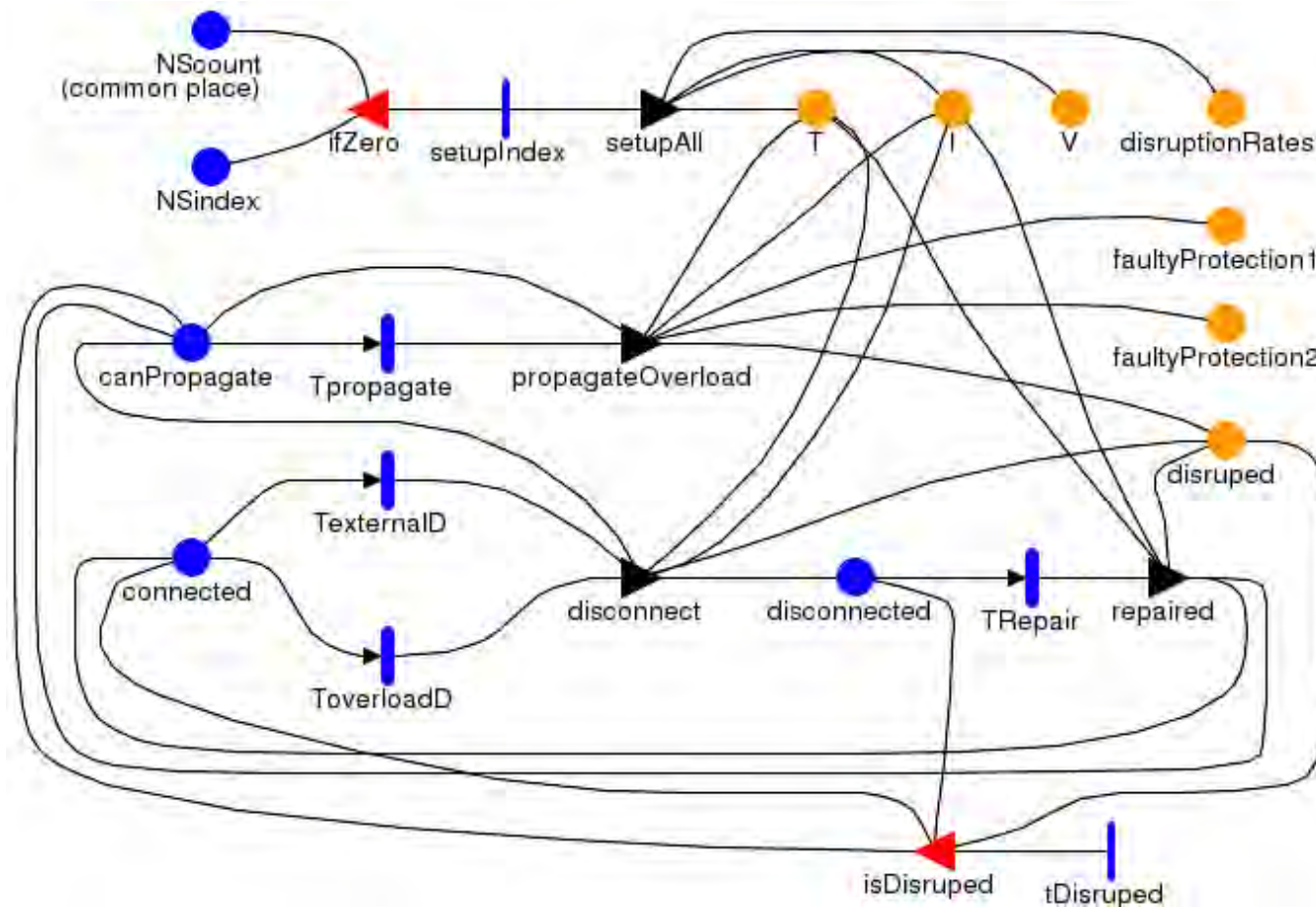
Feasibility of the modeling framework, aiming to show:

- **How some basic framework characteristics can be actually obtained**
- **Model construction of a simple EPS instance focusing on**
 - Substations
 - Protections
 - Local Tele-control systems
 - Regional Tele-control systems

Feasibility study - 2

- ❖ Feasibility of the modeling framework using the multi-formalism/multi-solution tool **Mobius**
- ❖ Formalism for models representation: **Stochastic Activity Networks (SAN)**
- ❖ Motivations for this choice:
 - **Mobius provides features to support the framework characteristics (points A1. - A5.; B1. - B4.)**
 - **It also supports multiple solution methods (analytic, simulation) and combination of solutions obtained through different methods.**

Modeling a Substation



SAN of a single N_s

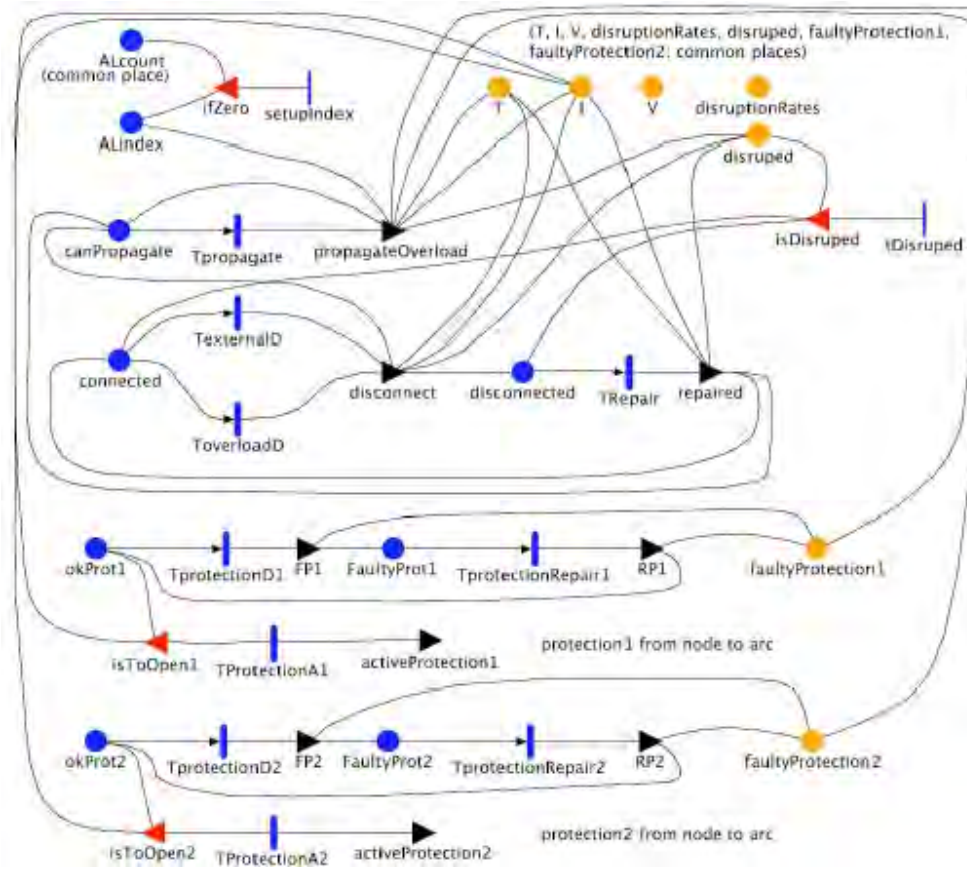
Major SAN elements - 1

- The extended place **T** (common place among the replicas) is an **array of array** of **short** type and represents the topology: **T[i,j]=1** means component *i* is connected to component *j*, otherwise its value is **0** (**A2.**, **B3.**)
- The extended places **I** and **V** (common places among the replicas) are **arrays** of **struct** type and describe the characteristics of the electrical parameters (only current and voltage, for simplicity): e.g., **I[j]** represents the current flow associated to component *j*, and relative threshold values for overloads and breakdown (**A2.**, **B4.**)

Major SAN elements - 2

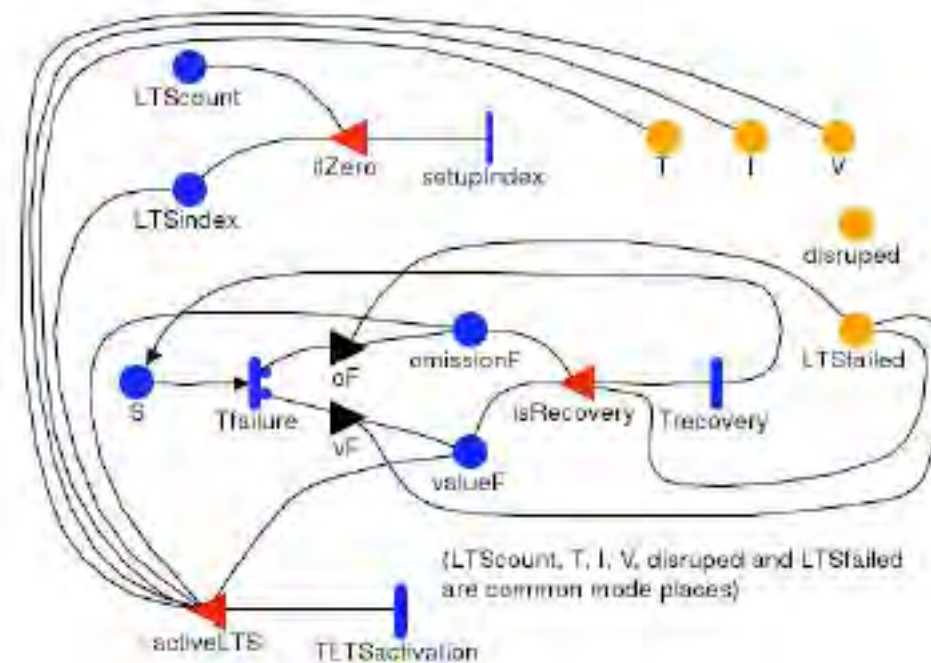
- The input gate **ifZero** enables to distinguish each replica when the N_S model is replicated (**B2.**)
- The function **propagateOverload()** is in charge of determining the new values of T and of the electrical parameters, following an event of overload of the current flow (it calls external functions, **A4.**)
- The rate of the activity **ToverloadD** (time to the occurrence of an internal disruption) depends on the current flow of the component (**A3.**)

Modeling protections



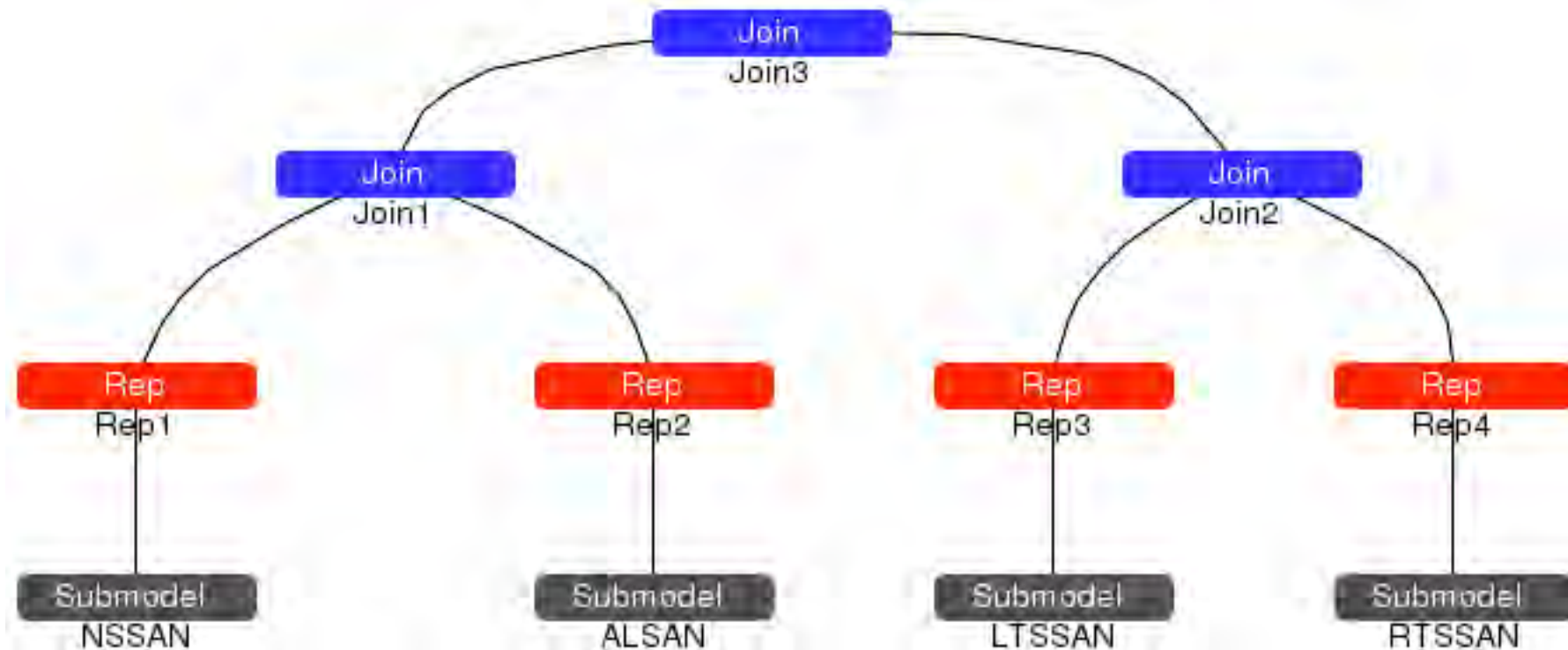
SAN for protections inside AL

Modeling a local Tele-operation system



SAN for LTS

Building part of an instance of EPS



- Replication and composition of the template models is performed through the **Rep** and **Join** operators (B1.)
- The replicas interact through common places (B2.)

Conclusions

- Definition of a modeling framework to analyze the interdependencies between the electrical infrastructure EI and the control information system ITCS
- Still preliminary studies, but relevant contributions to
 - The analysis of the structure and behavior of the EI and ITCS subsystems, including their failure models and states definitions;
 - The identification of the major challenges the modeling framework has to deal with, and discussion of possible approaches to cope with them;
 - The implementation of a few basic modeling mechanisms inside the Mobius modeling and evaluation environment, to support the feasibility of the proposed approach through an existing tool.

Next steps

- Further investigations on the appropriate level of model's details for EI and ITCS
- Extension and refinements of the modeling mechanisms
- Verification of the applicability of the approach on a simple but complete EPS example
- Study of the solution aspects
-

Main references

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