

# **From Analyzing System Failures, to Investigating Crimes**

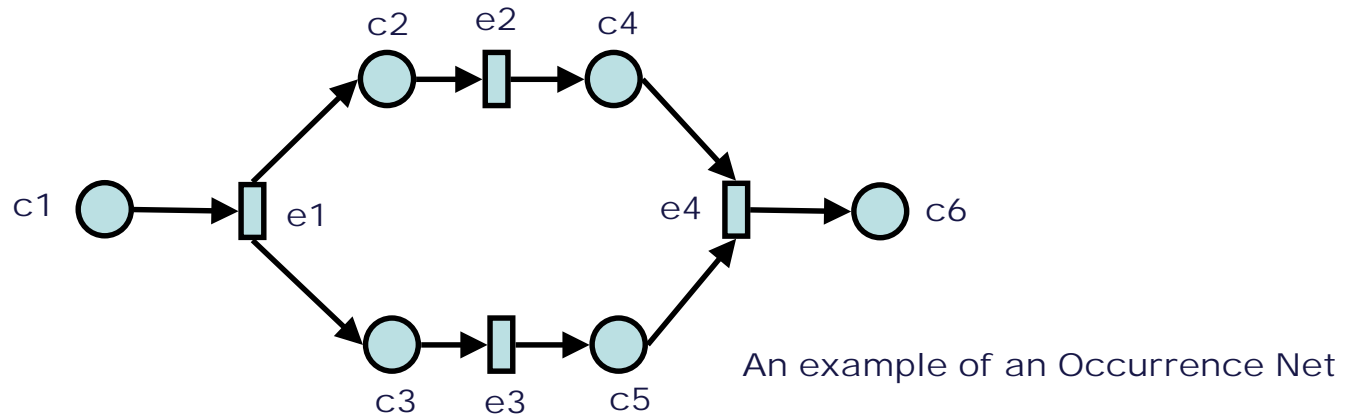
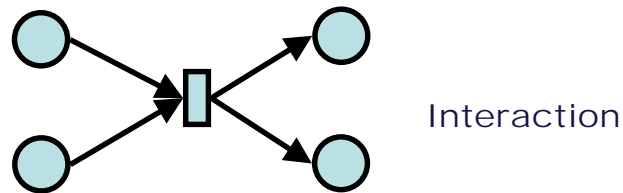
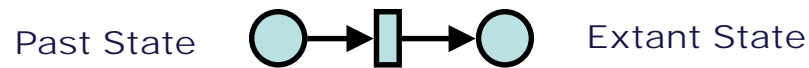
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# Our Current Theoretical Starting Point

- **Occurrence Nets (ONs)** are a forty-five year old mathematical formalism for representing **causality** and **concurrency** information concerning a ***single execution of a (in general asynchronous) system.***
- ONs are directed acyclic graphs that portray the (alleged) past and present, or the predicted, activity of a system, in terms of conditions (i.e. **states**), transitions (i.e. **events**) and arrows (representing known or alleged **causality**).
- (An ON can be viewed as a generalisation of a “sequential program trace”.)
- They can be represented as diagrams – good for tutorials, and for illustrating the basic ideas – but ONs are often represented algebraically, hidden from their users *inside* powerful fully-automated computer tools.
- They are much used in the computer industry, e.g. inside model-checking tools for validating system designs, and even for automatically creating (“synthesizing”) VLSI chip designs.

# Occurrence Nets

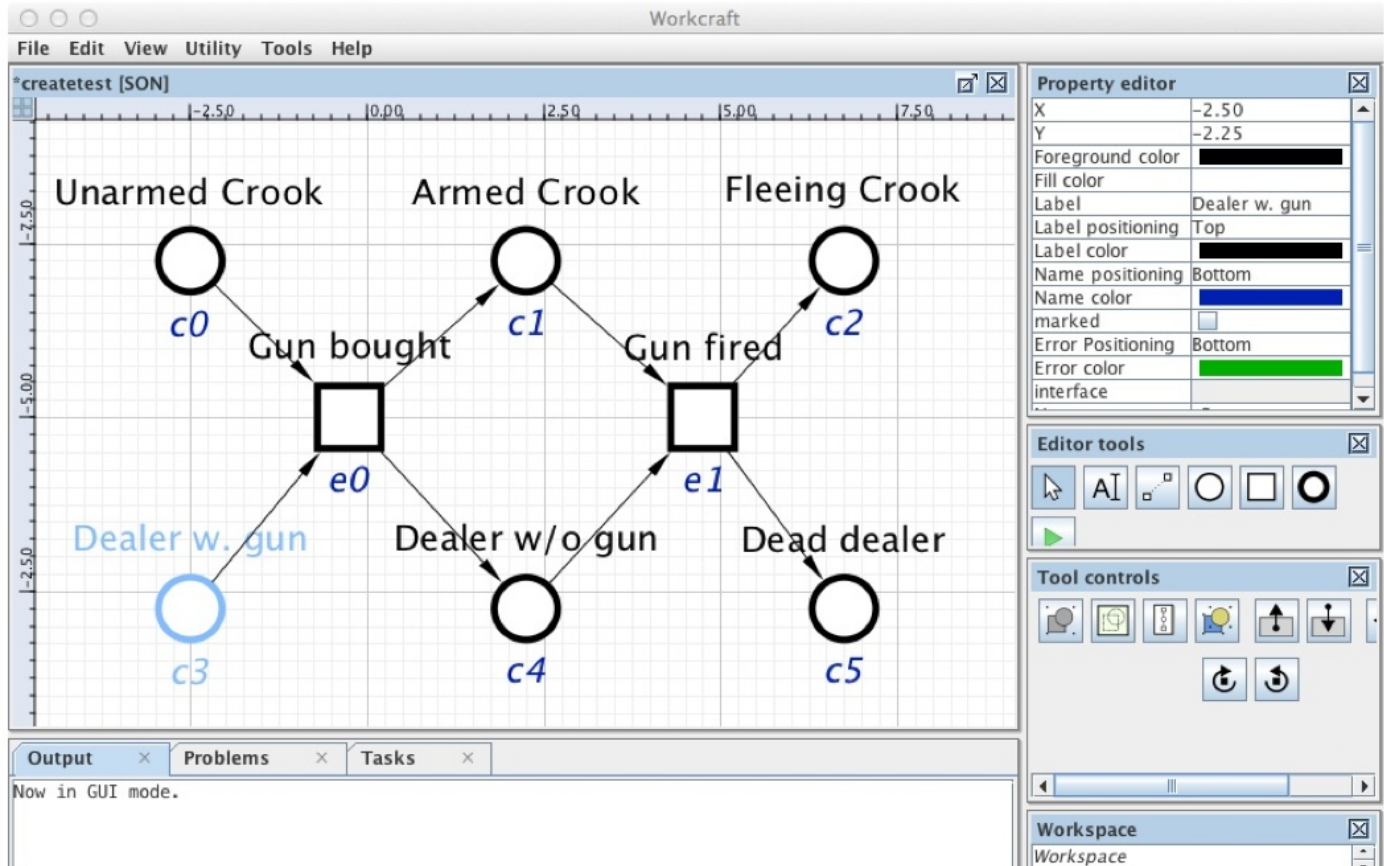
(a formal graphical notation)



# Occurrence Nets at Newcastle

Much work in ASL (Newcastle's joint EE/CS Asynchronous Systems Laboratory), on system design, validation and synthesis, uses ONs.

ASL's most recent interactive tool is WORKCRAFT (an infrastructure for interpreted graph models). See <http://workcraft.org/>



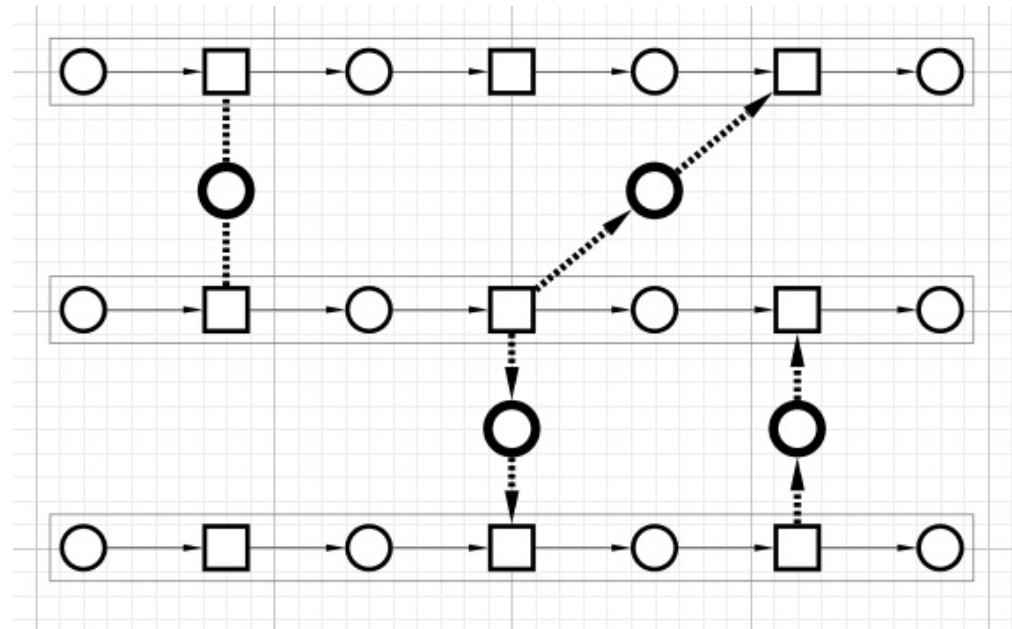
The screenshot displays the Workcraft application window with the following components:

- Editor window:** The main workspace showing an Occurrence Net (ON) diagram. The diagram consists of nodes and edges:
  - Nodes:  $c_0$  (Unarmed Crook),  $c_1$  (Armed Crook),  $c_2$  (Fleeing Crook),  $c_3$  (Dealer w. gun),  $c_4$  (Dealer w/o gun),  $c_5$  (Dead dealer),  $e_0$  (Gun bought), and  $e_1$  (Gun fired).
  - Edges:  $c_3 \rightarrow e_0$ ,  $e_0 \rightarrow c_0$ ,  $e_0 \rightarrow c_1$ ,  $c_1 \rightarrow e_1$ ,  $e_1 \rightarrow c_2$ ,  $e_1 \rightarrow c_4$ , and  $c_4 \rightarrow c_5$ .
- Property editor:** A panel on the right showing properties for the selected element (Dealer w. gun), including X and Y coordinates, foreground and fill colors, label and name positioning, and error handling options.
- Editor tools:** A panel on the right containing icons for selection, text, and various geometric shapes (circle, square, oval).
- Tool controls:** A panel on the right with icons for zooming, panning, and other navigation functions.
- Utility window:** A panel at the bottom left showing tabs for Output, Problems, and Tasks. The Output tab is active, displaying the message "Now in GUI mode."
- Workspace:** A panel at the bottom right showing the current workspace name.

# Structured Occurrence Nets

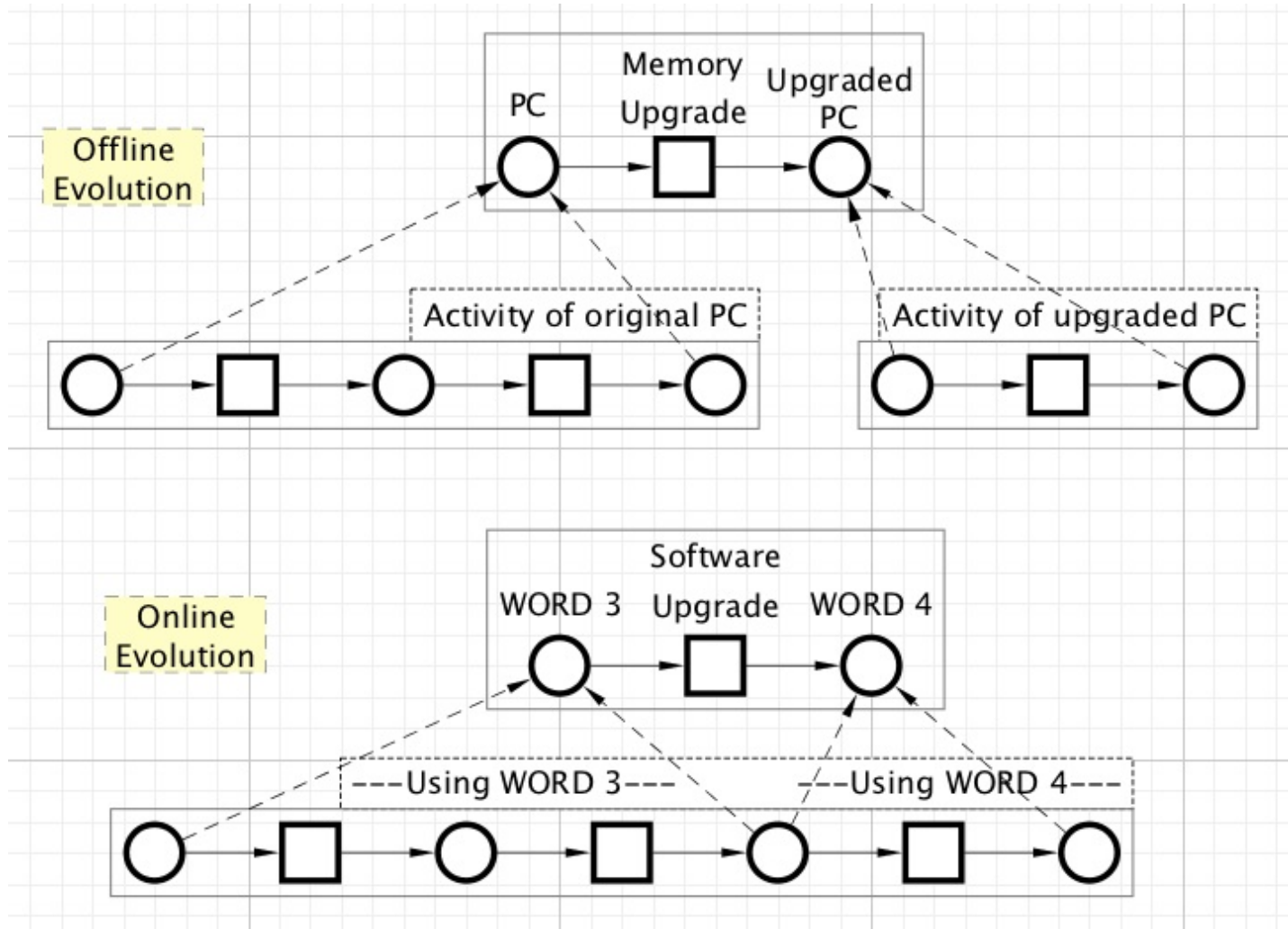
- A **Structured Occurrence Net** (SON) is a set of formally-related Occurrence Nets (using several forms of relation and hence abstraction).
- These include **behavioural abstraction** and **temporal abstraction**.
- SONs, like ONs, are acyclic – and so respect standard causality rules.
- SONs, unlike ONs:
  - enable the activities of different component systems to be readily distinguished
  - provide (through behavioural abstraction) a direct means of modelling the activity of an evolving system, so that
  - their structuring makes them suitable for much more complex systems and situations than ordinary (“flat”) ONs.
- They are of potential relevance to the tasks of verifying and synthesising (asynchronous, i.e. real) systems (of systems)
- But here I concentrate on the task of **analyzing system failures**, i.e. of determining what fault(s) caused what failure(s) – **using crimes as some of the failure examples**.

# Multiple Systems



- Basic ONs are good for single (non-evolving) systems. (If you use a large ON to show the activity of a set of interacting different systems, it will not be clear which system is responsible for which activity.)
- But by delineating the ONs that relate to different systems, and using explicit ***communication relations*** to represent their (synchronous or asynchronous) interactions, we can construct a **Communication Structured Occurrence Net (C-SON)** to simplify the modelling and analysis of large systems of systems

# (Simple) Examples of Behavioural Abstraction



Note – Such behavioural abstractions *cannot* be represented in ordinary occurrence nets

# Failure Analysis

- Failure analysis can involve following links in ONs **backwards** from a failure in order to identify causes, and then **forwards** to identify further errors and hence further potential failures.
- Behaviour relations between ONs in a SON can similarly be followed in each direction, to trace fault/error/failure chains between an evolving system and the activities it performs.
- Other types of relations between ONs can also be involved in such analysis.
- The identification of failures, errors and faults as such requires additional information, e.g. obtained from system specifications, or users' complaints.
- Such identifications are in principle, and often in practice, made by other (judgemental) systems, whose activities can also be modelled by ONs.



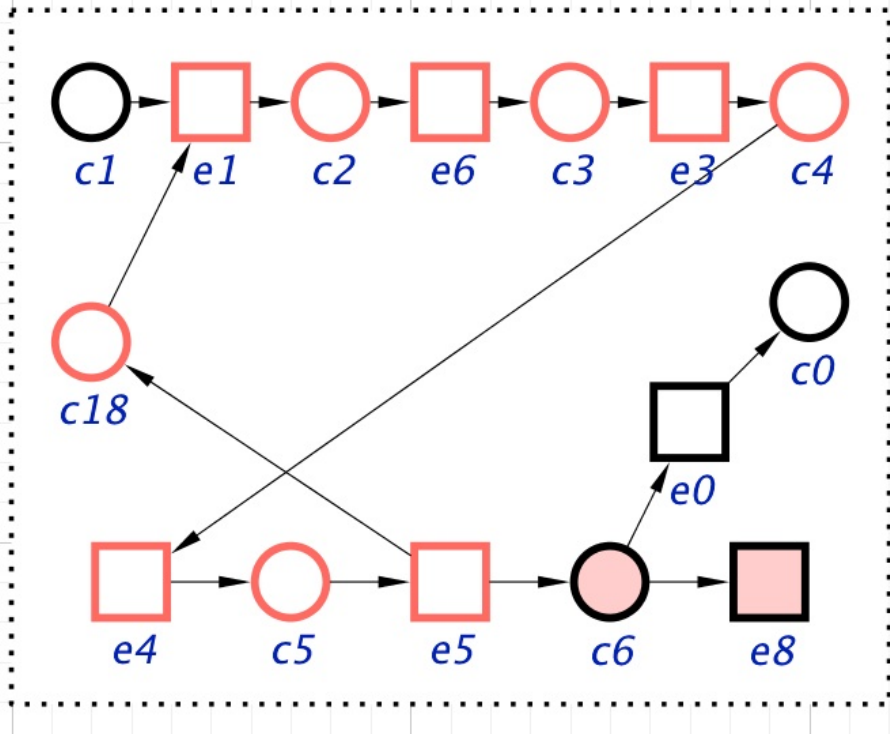
# The UNCOVER Project

- A three-year project, now into its second year, funded by the Engineering and Physical Sciences Research Council (EPSRC).
- The project involves research on extending the theoretical foundations of SONS, on tool support for SONS, and on potential application areas.
- The tool support is based on the WORKCRAFT infrastructure for interpreted graph models.
- The prototype tool that has been developed in UNCOVER is called **SONcraft**.
- One of UNCOVER's chosen illustrative application areas is crime/accident investigation support – the others are system verification (of VLSI chip designs), and on-line deadlock detection in networks.

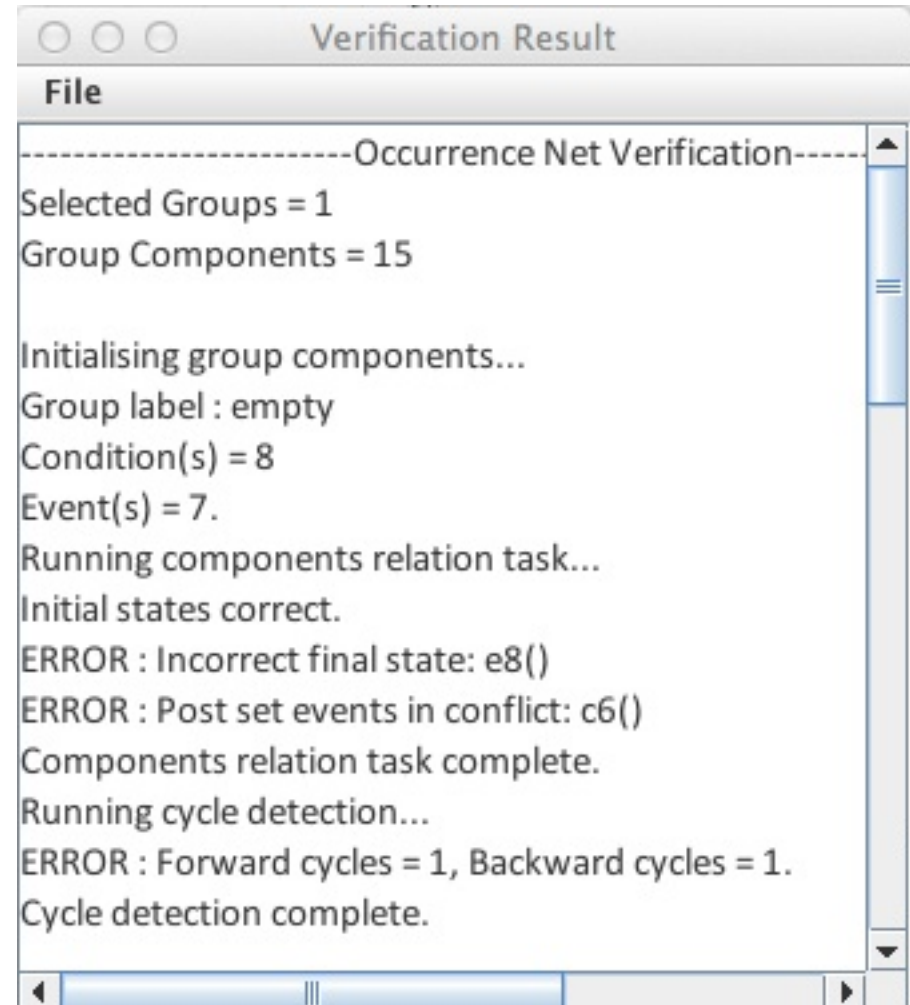
# UNCOVER's SONCRAFT Tool

- Implemented (by Bowen Li) as a plug-in to WORKCRAFT
- So far it provides graphic support for editing and portraying :
  - Occurrence Nets (ONs)
  - Structured Occurrence Nets (SONs) incorporating behaviour relations
  - Multiple communicating ONs
  - (Basic) behavioural abstraction and temporal abstraction
  - Basic support for multi-page diagrams
- It enables such ONs and SONs to be verified, with respect to the formal rules of SON and ON validity, e.g.
  - freedom from cycles, caused by arcs within ONs, and by communications or behaviour relations between ONs
  - the requirement for ON fragments to start and terminate in places, not events
  - the fact that places must not have multiple incoming or outgoing arcs.
- And it allows ONs and SONs to be “simulated”, i.e. for a user to explore a step at a time “what causes what”, in particular what errors have been propagated from one or more identified faults.
- Some example SONcraft screenshots follow.

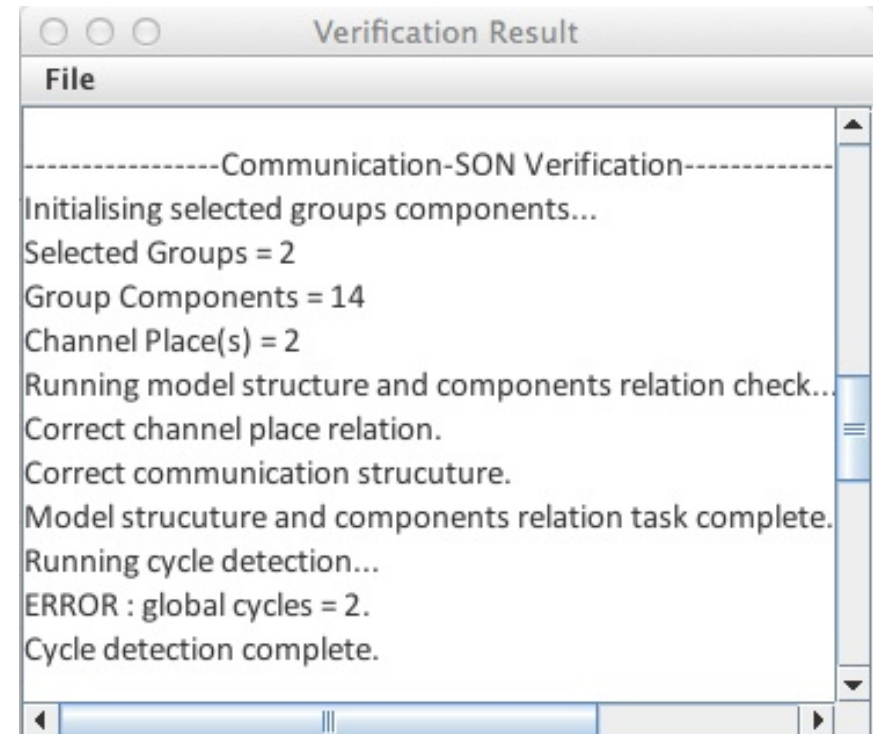
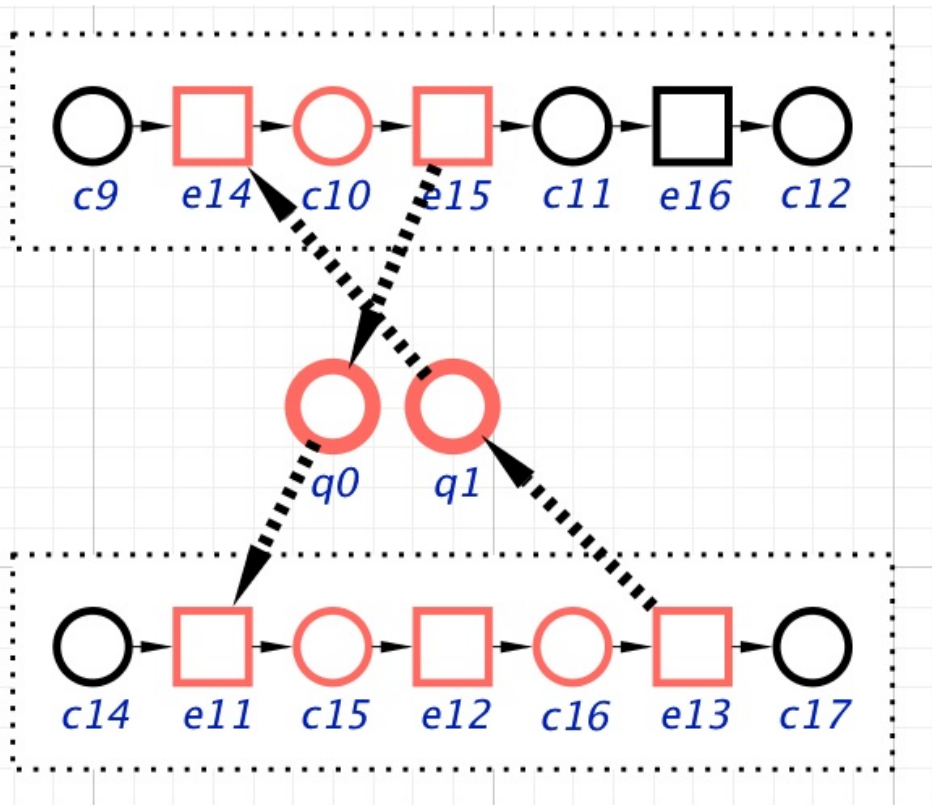
# Verification of an ON



Shaded events and conditions are invalid, ones with red borders are part of a cycle

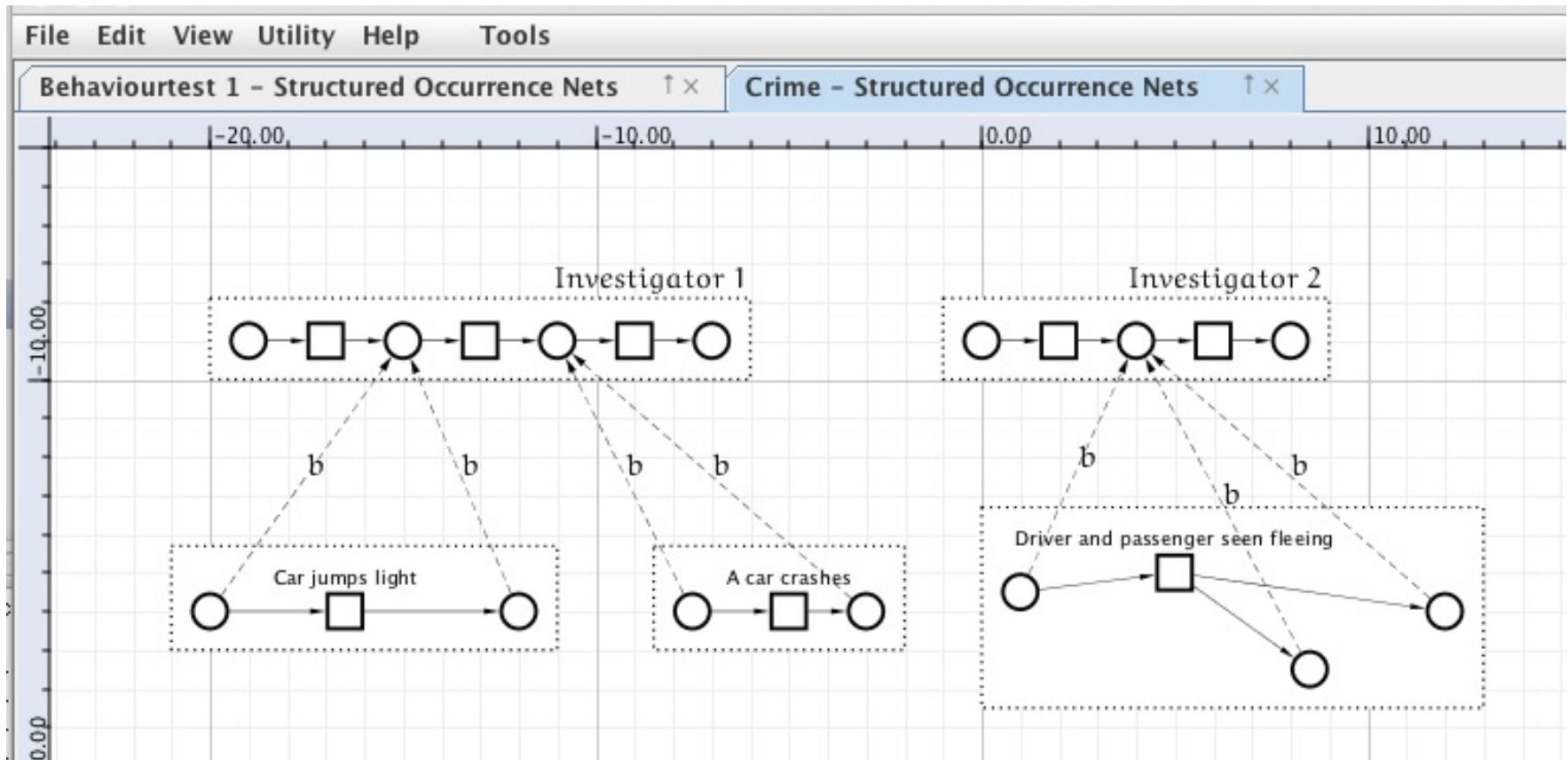


# Verification of a Communication SON



Events and conditions with red borders are part of a cycle involving asynchronous communications links joining multiple ONs

# Recording an Investigation



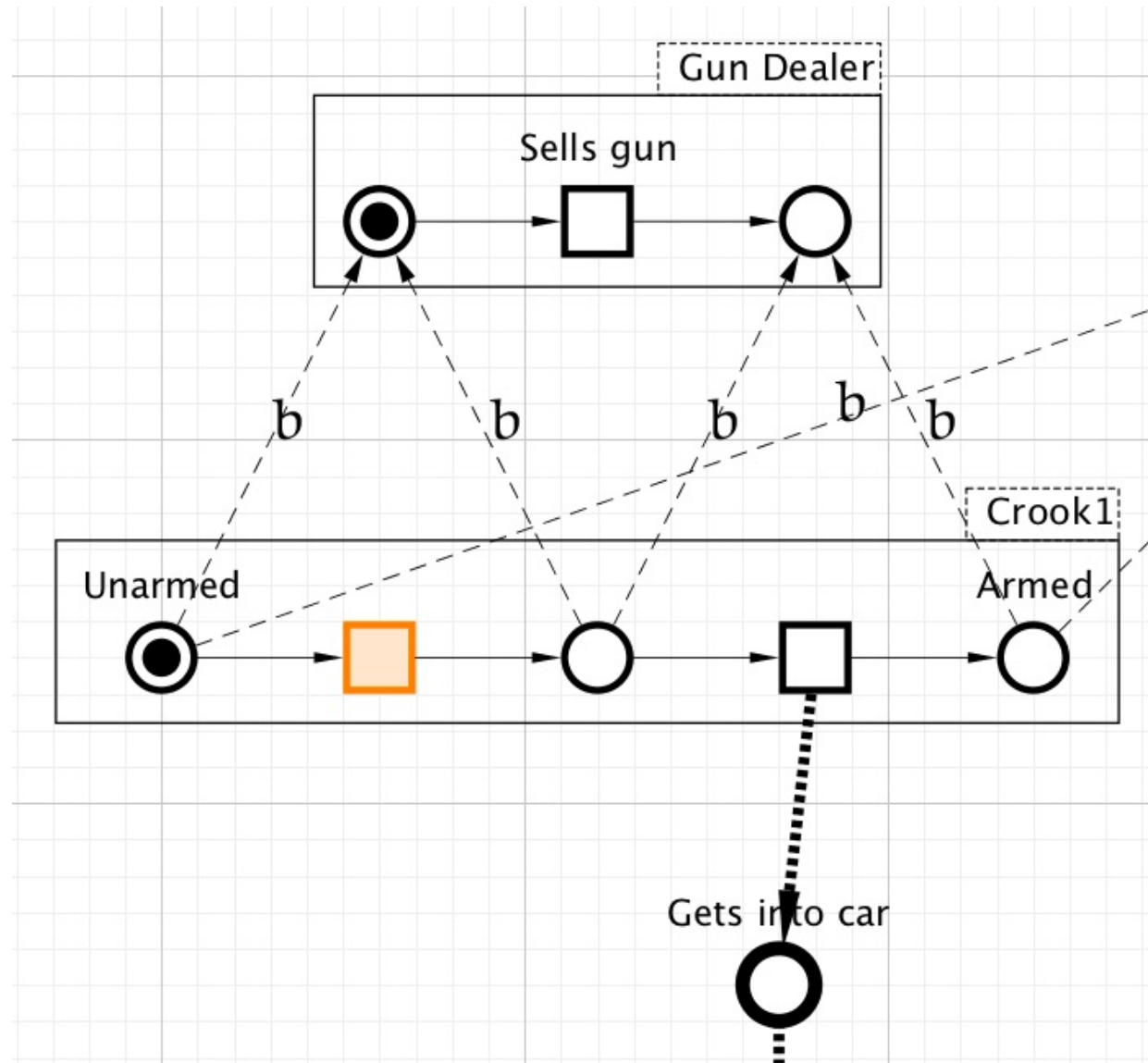
This SONCRAFT screenshot is interpreted as showing which investigator acquired and recorded what information when about a possible crime; it makes use of behavioural abstraction.

# SON Simulation

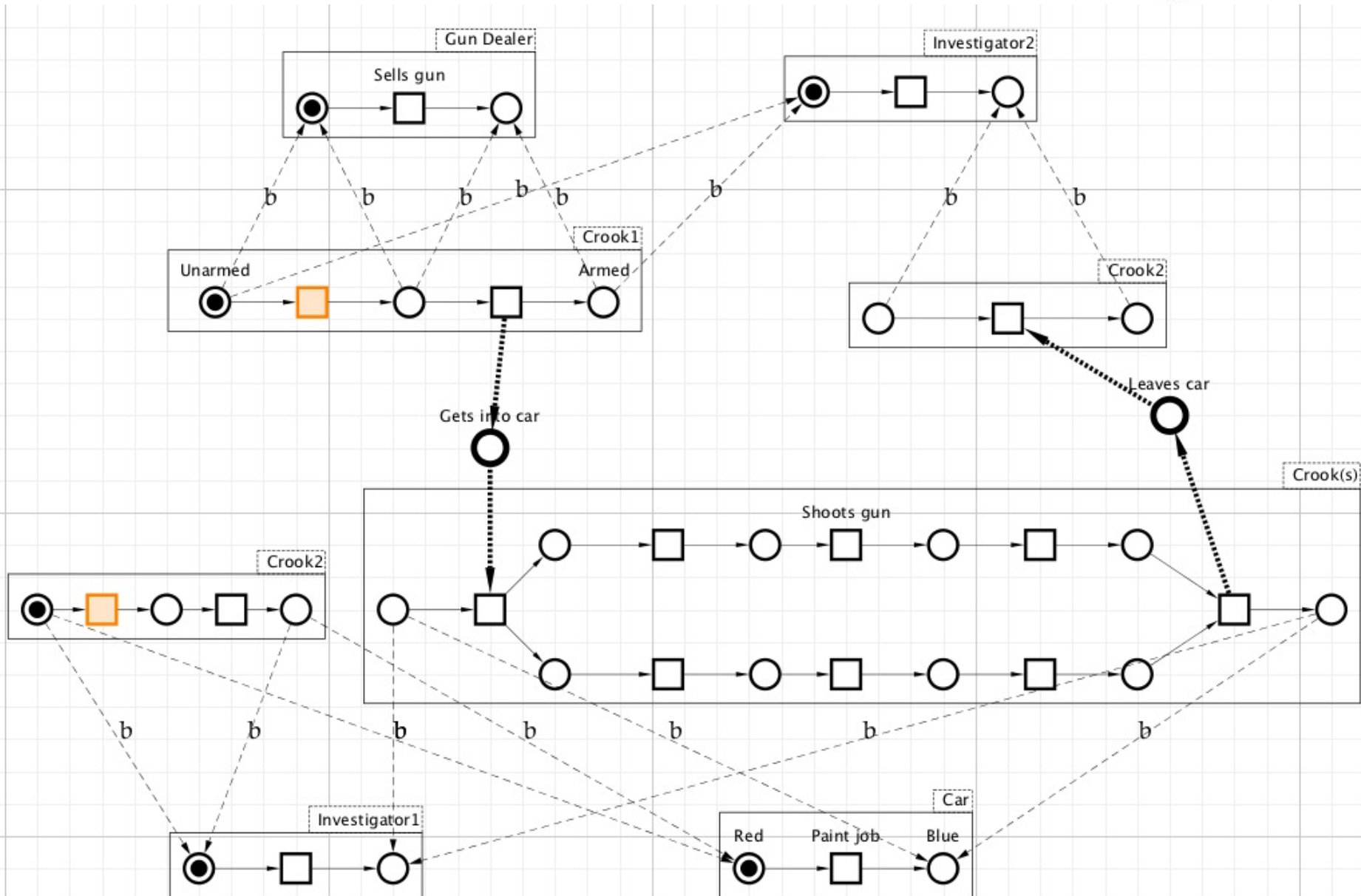
Simulation models error propagation – “reverse simulation” can model fault identification.

The figure shows part of a SON representation of a crime and its investigation.

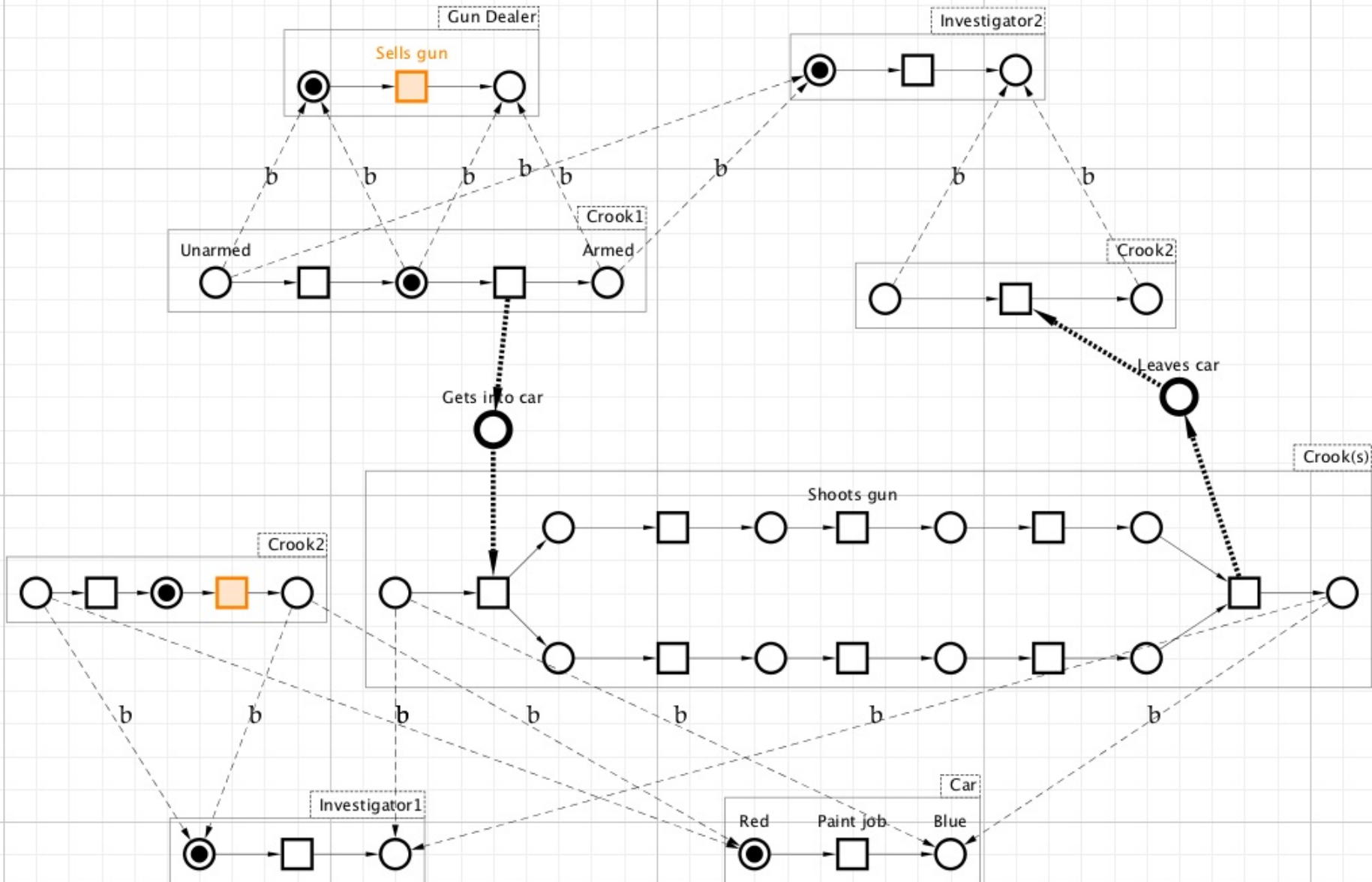
Places with black tokens are “active” - i.e. ready to contribute to an event. One can click on a chosen event that is coloured (i.e. able to proceed), to see the results of a single execution step.



# A crime and its investigation (1)



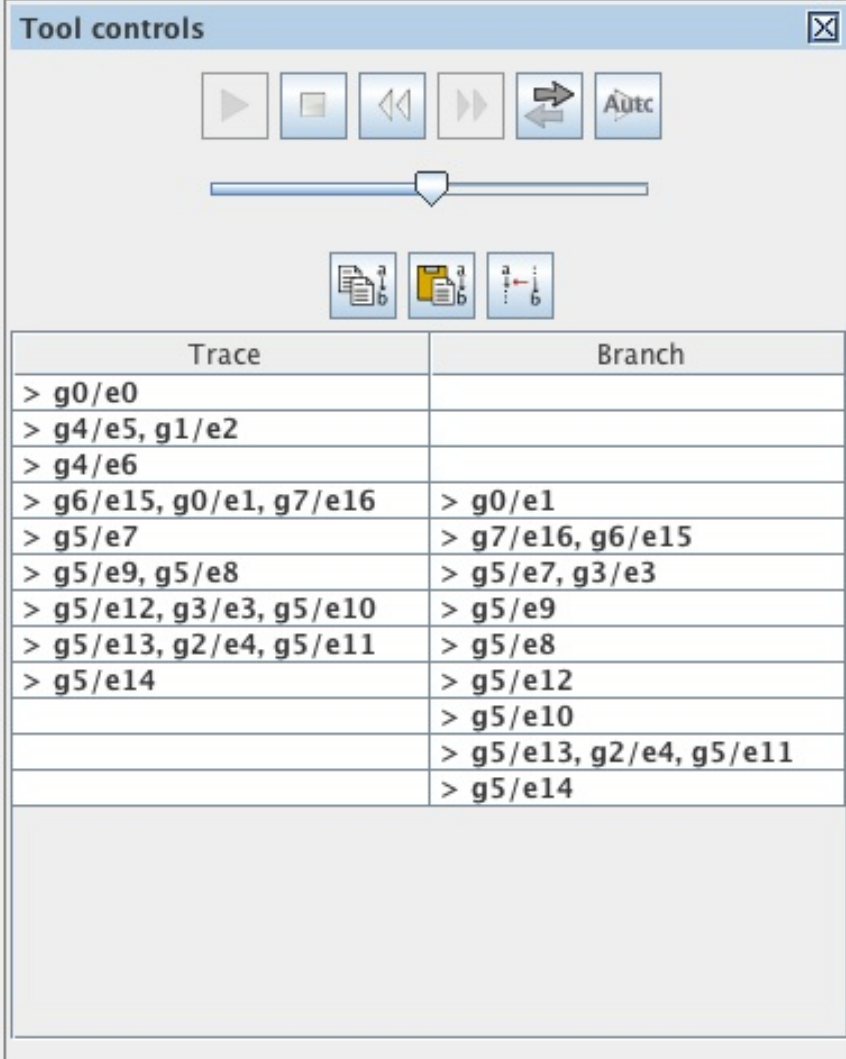
# A crime and its investigation (2)





# Simulation Control

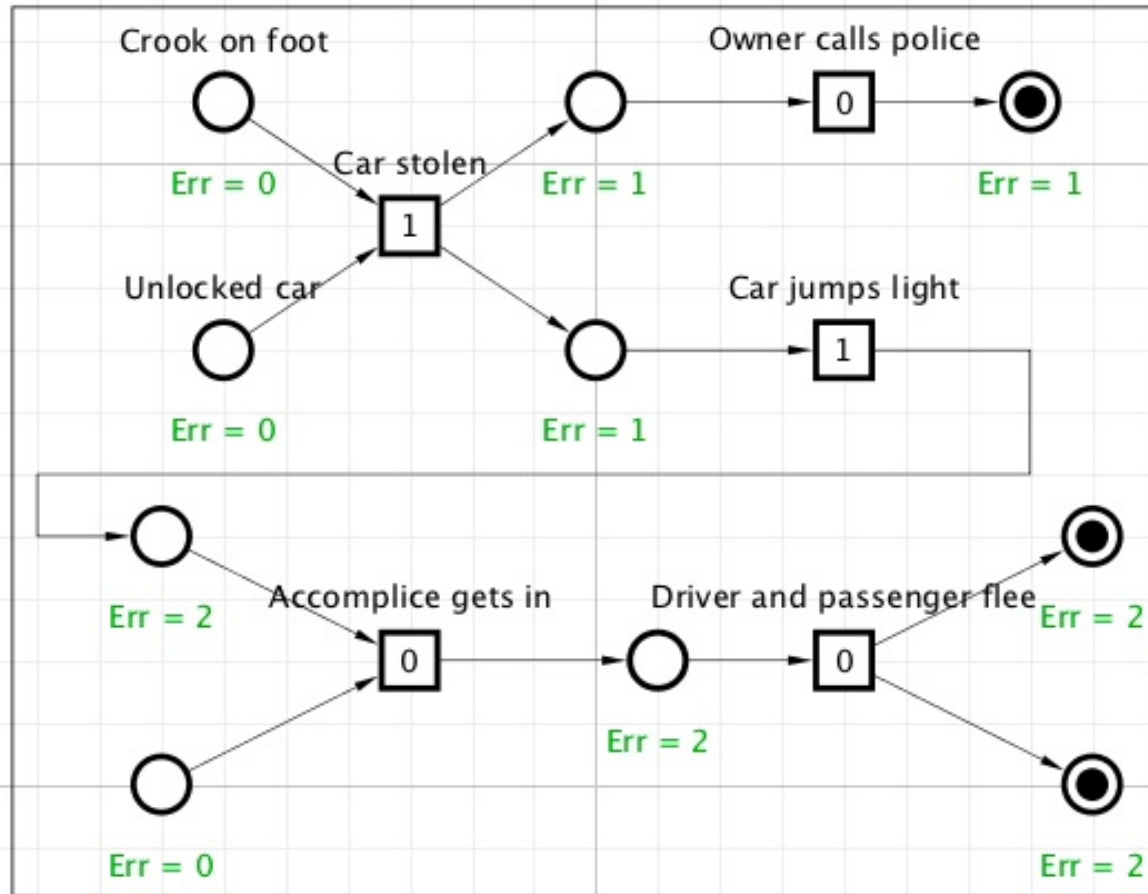
- Simulation can be performed forwards or backwards, and repeatedly reversed, while exploring fault/error/failure chains.
- As a simulation proceeds a 'trace' record is made of what event(s) occurred, and used to control the simulator.
- Such traces can also loaded with firing sequences produced by tools such as the reachability analyzer.
- Traces can be used to explore (forwards or backwards) through the sequence of recorded events, and to explore alternative choices of which enabled event(s) to select.
- Or they can be run through automatically, at a chosen speed.



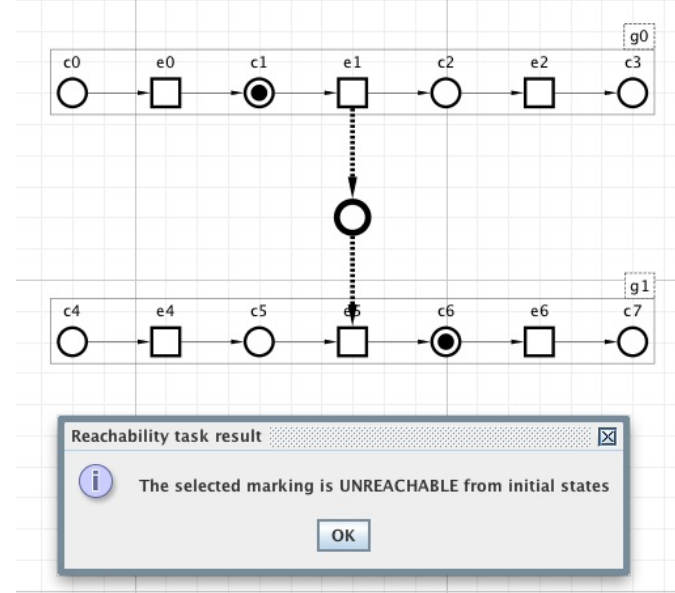
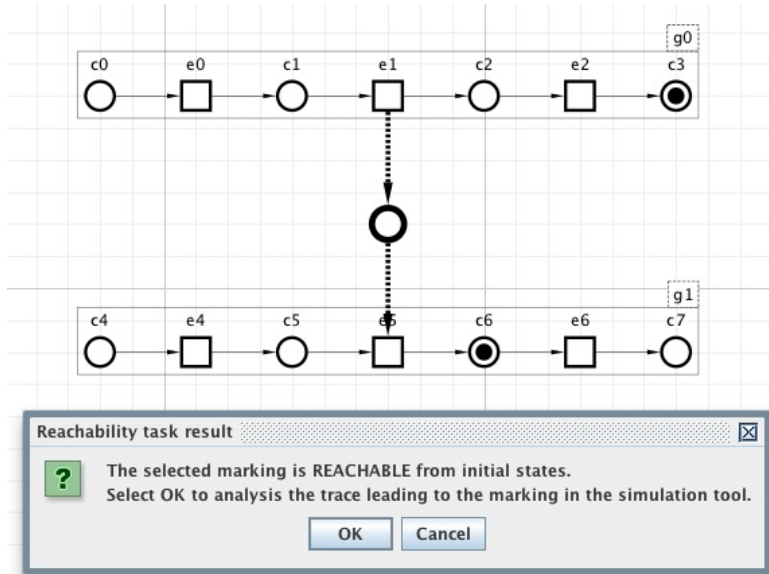
| Trace                   | Branch                  |
|-------------------------|-------------------------|
| > g0/e0                 |                         |
| > g4/e5, g1/e2          |                         |
| > g4/e6                 |                         |
| > g6/e15, g0/e1, g7/e16 | > g0/e1                 |
| > g5/e7                 | > g7/e16, g6/e15        |
| > g5/e9, g5/e8          | > g5/e7, g3/e3          |
| > g5/e12, g3/e3, g5/e10 | > g5/e9                 |
| > g5/e13, g2/e4, g5/e11 | > g5/e8                 |
| > g5/e14                | > g5/e12                |
|                         | > g5/e10                |
|                         | > g5/e13, g2/e4, g5/e11 |
|                         | > g5/e14                |

# Automated Error Tracking

- Each event can have a Fault bit, to indicate whether the user wishes to regard the event as a faulty one.
- If *error tracing* is turned on then the fault status of each event is flagged with a “1” or a “0”, “1” indicating a simulated fault.
- An error count is shown below each condition, set initially to “0”
- During simulation, each condition’s count shows the number of faults that have been passed before it was reached.



# Reachability Analysis



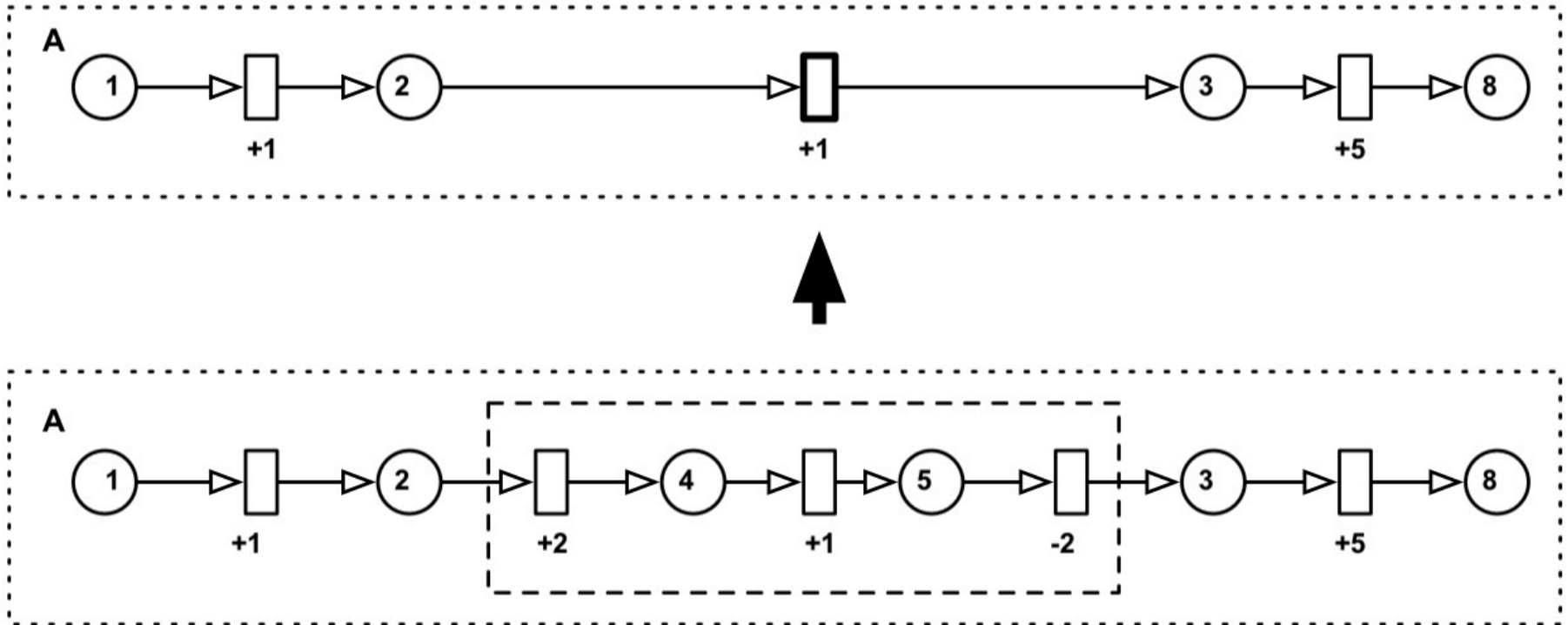
- The Reachability tool allows a user to check whether a given set of states (conditions and/or channel places) can be reachable *at the same time* from a model's initial states.
- (It checks whether any two of the given states are causally linked, i.e. must happen before the other.)
- If the given set of states is reachable (e.g. if crook A and crook B could have been in Bristol Docks simultaneously) then a trace of the events that would lead to this situation is passed to the simulation tool for playback or further analysis.

## Concluding Remarks

- SONs help reduce the complexity of complicated activity records, and to deal with evolving systems – and are we believe quite novel, and of wide applicability.
- Our EPSRC-funded “UNCOVER” research project involves both further theory development, and implementation of means of representing, analyzing and exploiting fully-general SONs.
- SONCRAFT is to be extended:
  - to deal with large (multi-sheet) diagrams,
  - to link with data sources (e.g. phone records),
  - to represent time (of event occurrences) and durations (of states), and
  - to support the modelling of multiple alternative (assumed) scenarios, associating probability estimates with these alternatives.
- We are discussing the potential of SONCRAFT as a front end to the CLUE crime investigation software, in order to provide investigators with new and enhanced analysis tools.
- SONs are involved in several other recently-submitted research project proposals (to EPSRC and EU), on topics including synthetic biology, cloud-based cybercrime, dynamic real-time system reconfiguration, risk reduction in marine transport, and automated traffic control.

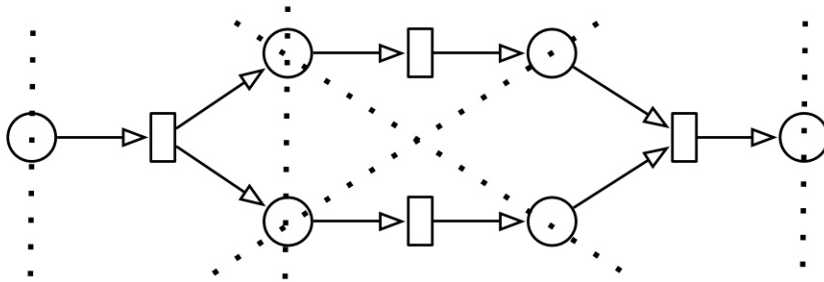


# (Simple) Temporal Abstraction – an arithmetic example

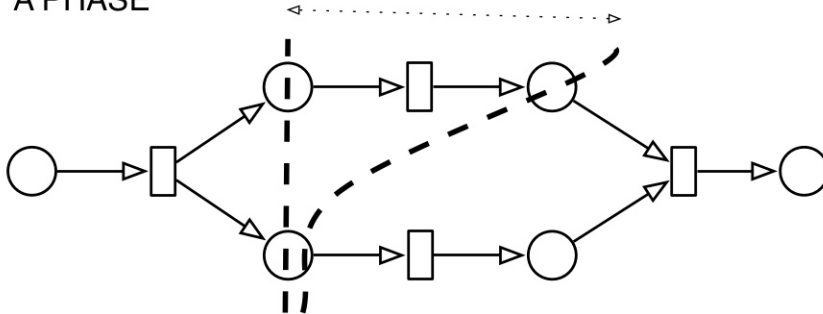


Note – The apparent simplicity of both behavioural and temporal abstraction soon vanishes when one starts considering asynchronous systems!

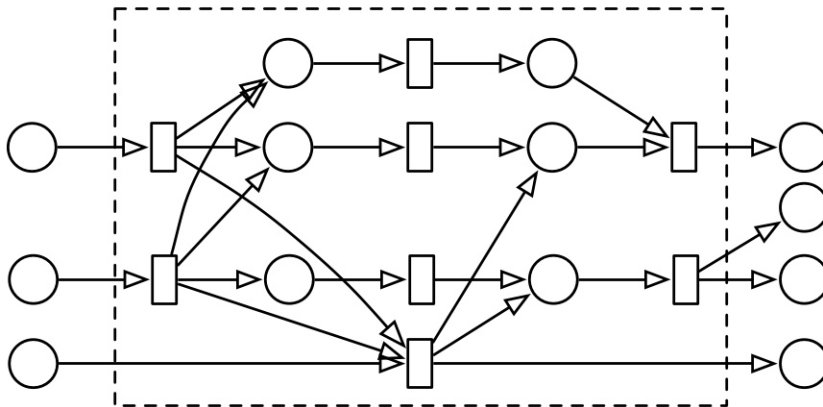
SOME CUTS



A PHASE



A BLOCK



# Cuts, Phases and Blocks

**Phases** are used for behavioural abstraction,  
**blocks** for temporal abstraction