Byzantine Fault Tolerance in Dynamic Distributed Systems

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Advent of Complex Distributed Applications

- Peer-to-peer
- Sensor Networks
- Mobile networks
- Cloud computing federations
- Internet supercomputing
- Smart environments
Spectrum of Possible System Models

Orderly

Static Managed Distributed Systems

- Air traffic Control
- Cloud Computing
- Peer-to-peer

World

Chaotic

Dynamic Unmanaged Distributed Systems

- Mobile ad-hoc Systems
Uncertainty in Dynamic Distributed Systems

- Static Distributed Systems:
  - Lack of temporal knowledge
  - Failures (including byzantine ones)
  - Unknown communication delays

- Dynamic Distributed Systems
  - Same issues as in static distributed systems, plus
  - Non-monotonic and unknown size of the system
  - Potentially changing properties of the “universe”
  - Unclear notions of efficiency, effectiveness, scalability

- Solid theoretical foundations
- Precise problem specifications
- Rigorously correct solutions
Distributed Storage Service

- Distributed Storage Service is one of the fundamental abstractions to build dependable applications
  - Main requirements: availability, consistency, robustness

- Modern distributed systems that host storage services are exposed to several vulnerabilities:
  - Asynchrony
  - Crash Failures
  - Attacks from malicious processes (i.e. byzantine failures)
  - Maintenance procedures produce churn
Object Abstraction: The Regular Register

A register is a shared variable accessed by processes through **read** and **write** operations.
Regular Register: write()

The writer process \( p_w \) wants to write the value \( v \). A subset of processes participate to the register computation. \( p_w \) sends a broadcast message (WRITE, \( v \), sn).

... in the meanwhile processes join and leave the computation.

OBS. Only processes belonging to the computation when \( p_w \) starts the write and that remain in the computation for all the time of the write will maintain the updated copy of the register.

Active Processes keeps the state of the computation.
BFT storage in Static Distributed Systems

- **State Machine Replication Approach**
  - [3] uses $2f + 1$ server replicas, and requires that every non-faulty replica agrees to process requests in the same order.

- **Quorum Based Approach**
  - [1] wait-free single-writer/multi-reader atomic register
    - $n \geq 3f+1$
    - two-phase reading and two-phase writing
  - [2] safe variable with assuming at least $5f$ replicas
    - $n \geq 5f$
    - one-phase reading and one-phase writing

Storage Service in Dynamic Distributed Systems

- [1] presents a Reconfigurable Atomic Memory for Basic Object (RAMBO) on top of a distributed systems where processes can join or fail by crashing.
  - Based on Consensus

- [2] shows that a crash resilient atomic register can be realized without consensus, and thus implementable on a fully asynchronous distributed system
  - Assumption of majority of correct processes in any reconfiguration

- [3] provides a crash-resilient regular register in the presence of churn

Related work

1. BFT Registers in Distributed Systems with churn
      1. Assumption of bounded execution time for each operation
      2. Bound on the churn depending on the duration of each operation

   1. Synchronous System prone to continuous churn


System Model

**Clients System**
- Composed by a finite arbitrary number of processes

**Servers System**
- It is dynamic
  - New servers are connected along time
  - Servers can be disconnected

**Authenticated Communication**
Impossibility of realizing a regular register

- [1] shows that it is not possible to implement a register in a fully asynchronous distributed system prone to continuous churn.

- **Eventual Synchrony Assumption**
  - There exist a time $t$ such that any message $m$ broadcast/sent from a process $pi$, at some time $t' > t$ is delivered by time $t' + \delta$ unless $pi$ leaves the computation between $t'$ and $t' + \delta$.

Computation Model

Clients are not byzantine, but can crash

No information about register state

Clients trigger read() and write() operations
Computation Model

- Initially n servers are part of the register computation
- Servers do not know how is currently in the computation
- Up to f byzantine failures
- Servers maintain locally a copy of the register value
- Alternating periods of churn and stability
  - No stable processes
  - In churn periods the servers set is continuously changing

Write \( v \) \hspace{5mm} \text{Read } () \hspace{5mm} \text{Join_Server}()
Correct Servers’ Life Cycle

Servers Computation $C_S$

Active

Join_Confirmation

Joining

Join()

Join()

Leave()

Leave()

Disconnect()

Up

Connect()

Servers System $U_S$

Down
Churn Model

Servers Computation $C_S$

Active

Join_Confirmation

Joining

Leave()

Assumption

$|A(t)| \geq n - J$

$|C(t)| \in [n, n - J]$

$n = \# \text{ of servers in the computation at time } t_0$

$J = \text{maximum number of concurrent joining processes}$
Safe Register Specification

- **Termination**
  - If a correct process (either a client or a server) participating in the computation invokes an operation and does not leave the system, it eventually returns from that operation.

- **Validity**
  - A `read()` operation, not concurrent with any `write()`, returns the last written value before its invocation. In the case of concurrency, a `read()` may return any value.
Issues

- **Byzantine servers**
  - Possible collusions to compromise the register state
    - Given $f$ faulty servers, at least $2f+1$ values are needed to filter out faulty ones

- **Churn**
  - The set of replicas maintaining the register value continuously change during time
    - The current value may disappear after a certain amount of time

- **Eventually Synchronous Communications**
  - write messages can be missed by new servers
  - ack messages can be lost due to servers departures
Algorithm

- **General Idea:**
  - Read and Join Operations should be as fast as possible (1 phase)

- Extension of Malkhi-Reiter byzantine quorums [1] to distributed system prone to churn
  - Read() and write() operations are performed on a quorum of n-f-J servers
  - The join() operation is a particular case of read

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read() and write(v) operations

- **write(v)**
  - Client periodically sends the value and its timestamp
  - Servers acknowledge the new value
  - Client waits for $n - f - J$ ack and then ask for confirmation
  - Servers confirm the new value

- **read()**
  - Client periodically ask for the current value
  - Active servers reply with a pair $<v, ts>$
  - Client waits for $n - f - J$ replies and then select the most frequent value
Join() Operation
Theorem

- **Validity**
  - If \( n \geq 5f + 3J \), then a read() operation that is not concurrent with any write(), returns the last value written before the read() invocation.

- **Termination.**
  - Let \( n \geq 5f + 3J \). If a process invokes join(), read() or write (), and does not leave the system, it eventually terminates its operation.
**Correctness (intuition)**

- Quorum size is $n - f - J$
- An Opaque Masking quorum system (as defined in [1]) exists if correct affected servers are more than
  - faulty answering to a read +
  - not affected ones

- Considering that joining processes are not faulty but only temporarily silent, this condition is true for $n \geq 5f + 3J$

- **Validity** is guaranteed by the existence of the quorum system
- **Termination** follows from the eventual synchrony

Conclusion and future work

- A safe register can be implemented also in the presence of both bounded churn and byzantine servers
- However...
  - A lot of replicas are needed to cope with this issues

- Some open questions for our future work
  - Can we remove the assumption of bounded $f$?
  - Can we handle rational behavior?
  - Other attacks?

- Main achievement: churn is a specific type of behavior that have to be handled appropriately!
Thank You!

Questions?!